

Exact point-optimal sign-based inference for linear and nonlinear predictive regressions

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Abstract

We propose point-optimal sign-based tests for linear and nonlinear predictive regressions that are valid in the presence of heteroskedasticity of unknown form and persistent volatility, as well as persistent regressors and heavy-tailed errors. These tests are exact, distribution-free, and may be inverted to build confidence regions for the parameters of the regression function. Point-optimal tests maximize power at a predetermined point in the alternative hypothesis parameter space, which in practice is unknown. Therefore, we suggest an adaptive approach based on the split-sample technique to shift the power function close to that of the power envelope. We then present a Monte Carlo study to assess the performance of the proposed “quasi”-point-optimal sign test by comparing its size and power to those of certain existing tests which are intended to be robust against heteroskedasticity. The results show that our procedures outperform classical tests. Finally, as predictors of stock returns are often highly persistent and lead to invalid inference using conventional tests, we consider an empirical application to illustrate the relevance of our proposed tests for testing the predictability of stock returns.

Keywords: predictive regressions, persistency, sign test, point-optimal test, exact inference, endogeneity, split-sample, adaptive method, projection technique

JEL Codes: C12, C15, C22

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1 Introduction

Numerous studies investigate the predictability of financial and economic variables using the past values of one or more predictors, as well as the horizon at which evidence in favor of predictability is prevalent. Most commonly encountered examples concern the predictability of stock returns using the lag of certain fundamental variables, such as the dividend-price and earnings-price ratios or the interest rates [see [Campbell and Shiller \(1988\)](#), [Fama and French \(1988a,b\)](#), [Campbell and Yogo \(2006\)](#), [Campbell and Thompson \(2008\)](#), and [Golez and Koudijs \(2018\)](#) among others]. Predictability in this context is generally assessed using the OLS regression of returns against said predictors and tested with conventional t -type tests. For instance, by utilizing this approach, [Fama and French \(1988a,b\)](#) and [Welch and Goyal \(2008\)](#) conclude that predictability in stock returns is not of economic significance at short horizons, yet the predictability power of the predictors increase at longer horizons. However, the regressors frequently considered in these studies are often highly persistent (near nonstationarity) with innovations that are correlated with the disturbances in the predictive regression of returns [see [Phillips \(2015\)](#) for a review]. In such situations, unless the predictor is strictly exogenous, we know that the OLS estimator of the coefficients, although consistent, will suffer from significant bias [see [Stambaugh \(1999\)](#), [Magdalinos and Phillips \(2009\)](#)]. As a result, the t -statistic will have a nonstandard distribution in finite samples which leads to invalid inference [see [Mankiw and Shapiro \(1986\)](#), [Banerjee et al. \(1993\)](#) and [Stambaugh \(1999\)](#) among others]. Moreover, inference based on consistent heteroskedasticity and autocorrelation corrected (HAC) approaches are shown to have poor finite sample performance under different forms of heteroskedasticity and nonlinear dependencies [see [Dufour and Taamouti \(2010\)](#)], which is of relevance in this setting, since some studies further suggest that stock returns' volatility are stochastic and highly persistent [see [Jacquier et al. \(2004\)](#) and [Hansen et al. \(2014\)](#)]. In this paper, we address the endogeneity issue inherent within a predictive regression framework, by deriving point-optimal sign-based tests (POS-based tests hereafter) in the context of linear and nonlinear models that are distribution-free, robust against heteroskedasticity of unknown form as well as serial (nonlinear) dependence, provided that errors have zero median conditional on their past and the past of the explanatory variables.

[Nelson and Kim \(1993\)](#) show that in a predictive regression setting, sample slope coefficients and the asymptotic standard errors of [Newey and West \(1986\)](#) are biased towards significant t -statistics, which increase with longer return horizons. Thus, they reduce the small-sample bias using bootstrap simulations, whereas [Stambaugh \(1999\)](#) further demonstrates that in the case of stationary regressors said bias can be corrected using a first order asymptotic bias correction procedure. [Amihud and Hurvich \(2004\)](#) and [Amihud et al. \(2008\)](#) adopt a similar process to reduce finite sample bias in regression coefficients for short return horizons, and more recently [Kan and Pan \(2021\)](#) adjust for the bias in the slope coefficient and the

standard errors in the context of long-horizon returns. However, studies by [Phillips and Lee \(2013\)](#) and [Phillips \(2014\)](#) show this approach to be infeasible in the presence of predictors that exhibit local-to-unity, unit-root or explosive persistency. Therefore, many inference procedures in this context address the issue of size distortions by considering local-to-unity asymptotics as proposed by [Chan and Wei \(1987\)](#) and [Phillips \(1987\)](#), where the key predictor variable is assumed to be integrated [[Lewellen \(2004\)](#)], or can be modeled as having a local-to-unit root [[Elliott and Stock \(1994\)](#), [Torous et al. \(2004\)](#), and [Campbell and Yogo \(2006\)](#), among others]. Notable studies under the local-to-unity dynamics employ an array of procedures, such as Bonferroni corrections [e.g. [Cavanagh et al. \(1995\)](#) and [Campbell and Yogo \(2006\)](#)], a conditional likelihood based approach [e.g. [Jansson and Moreira \(2006\)](#)], as well as the nearly optimal tests proposed by [Elliott et al. \(2015\)](#). In more recent works, [Kostakis et al. \(2015\)](#) and [Phillips and Lee \(2016\)](#) expand on the predictability literature by utilizing an extension of the instrumental variable (IV hereafter) procedure suggested by [Phillips et al. \(2009\)](#), to generalize inference to multivariate regressors with integrated and mildly explosive persistency. As far as IV procedures are concerned, [Ibragimov et al. \(2020\)](#) adopt a nonlinear instrumental variable estimation approach (where the instrument is a sign transformation of the predictor) that deals with the issues of persistent endogeneity and heavy-tailedness. Additionally, they propose nonparametric volatility correction to circumvent the problems caused by heterogeneous and persistent stock returns' volatility. Finally, a number of exact and nonparametric inference procedures within this context include the signed and sign-ranked statistics of [Campbell and Dufour \(1991\)](#) and [Campbell and Dufour \(1995, 1997\)](#), which are model-free and impose mild assumptions on the distribution of the error terms. These inference methods are useful in the presence of a single regressor and a nuisance parameter. Recent developments in distribution-free and exact tests include those proposed by [Gungor and Luger \(2021\)](#), which consider several prediction horizons, as well as test for predictability in quantiles.

The contribution of the POS-based tests proposed in our study is twofold: firstly, as the tests are distribution-free, they are valid in the presence of regressors with general persistency and different forms of nonlinear dependencies in finite samples, and do not suffer from discontinuity in the limiting distribution of conventional test statistics between stationary, local-to-unity and explosive autoregressions. Secondly, our tests possess the greatest power among certain parametric and nonparametric tests that are frequently encountered in practice and can easily be extended to multivariate testing problems.

In a recent study, [Dufour and Taamouti \(2010\)](#) propose simple point-optimal sign-based tests in the context of linear and nonlinear regression models, which are valid under non-normality and heteroskedasticity of unknown form, provided the errors have zero median conditional on the explanatory variables. These tests are exact, distribution-free, and robust against heteroskedasticity of unknown

form, and may be inverted to build confidence regions for the vector of unknown parameters. This work, however, is developed under the assumption that the errors are independent. The main motivation is to build point-optimal sign-based tests for linear and nonlinear predictive regressions that retain the advantages of the POS-based tests proposed by [Dufour and Taamouti \(2010\)](#). To extend this work, we recognize that under the alternative hypothesis the signs are no longer necessarily independent and the test statistic now depends on calculating the joint conditional distribution of the signs, which is computationally infeasible. Therefore, an additional assumption on the dependence structure of the conditional signs is needed to obtain *feasible* test statistics; namely, a Markovian assumption on the conditional signs.

By construction, our POS-based tests control size for any given sample. Under the null hypothesis of unpredictability, the tests are valid even in the presence of the bias problem pointed out by [Mankiw and Shapiro \(1986\)](#) and [Stambaugh \(1985, 1999\)](#), which affects the classical testing procedure for stock returns predictability. In addition, our tests do not impose any modeling assumptions on the predictors and are robust against heteroskedasticity of unknown form and/or serial (nonlinear) dependencies. The tests are point-optimal tests, which are useful in a number of ways and are particularly attractive when testing one financial theory against another. An important feature of these tests stems from the fact that they trace out the power envelope - i.e. the maximum attainable power for a given testing problem, which may be used as a benchmark against which other testing procedures can be evaluated. Finally, our tests may be inverted to build confidence regions for the parameters of the regression function.

As point-optimal tests maximize power at a nominated point in the alternative hypothesis parameter space, a practical problem concerns finding an alternative at which the power curve of the POS-based test is close to that of the power envelope. Following [Dufour and Torrès \(1998\)](#), [Dufour and Jasiak \(2001\)](#) and [Dufour and Taamouti \(2010\)](#), we propose an adaptive approach based on the split-sample technique to choose the alternative hypothesis. The latter consists of splitting the sample into two independent subsamples, where the first part is used to estimate the alternative hypothesis and the second part to compute the POS-based test statistic [see [Dufour and Iglesias \(2008\)](#)]. In a simulations exercise, [Dufour and Taamouti \(2010\)](#) find that using the first 10% of the sample to estimate the alternative and the rest to compute the test statistic, achieves a power that traces out the power envelope. We present a Monte Carlo study to assess the performance of the proposed “quasi”-POS-based tests by comparing its size and power to certain existing tests that are intended to be robust against heteroskedasticity. We show the superiority of our procedures in the presence of nearly integrated regressors and under different distributional assumptions and forms of heteroskedasticity.

The rest of the paper is organized as follows: in [Section 3](#), we propose exact POS-based tests in the

context of linear and nonlinear predictive regressions. Section 4 discusses the adaptive approach based on the split-sample technique for choosing the alternative hypothesis and computing the POS-based test statistic. Section 5 expands on the details of the construction of confidence regions using the projection techniques and provides a numerical example. Section 6 presents a Monte Carlo study to assess the performance of the POS-based tests by comparing their size and power to those of certain popular tests. Section 7 is devoted to an empirical application, in which the predictability power of certain fundamental variables on future stock returns is tested at different horizons and sampling frequencies. Finally, the paper is concluded in Section 8. Proofs are presented in Appendix 9.

2 Framework

In this Section, we adapt the framework considered by Coudin and Dufour (2009) to a predictive regression setup, where the dependent variable is now regressed against a lagged predictor. Consider a stochastic process $Z = \{Z_t = (y_t, \mathbf{x}'_{t-1}) : \Omega \rightarrow \mathbb{R}^{(k+1)}, t = 1, 2, \dots\}$ defined on a probability space (Ω, \mathcal{F}, P) . Suppose that y_t can linearly be explained by the vector variable \mathbf{x}_{t-1}

$$y_t = \beta' \mathbf{x}_{t-1} + \varepsilon_t, \quad t = 1, \dots, T, \quad (2.1)$$

where y_t is a dependent variable and \mathbf{x}_{t-1} is an $(k+1) \times 1$ vector of stochastic explanatory variables, say $\mathbf{x}_{t-1} = [1, x_{1,t-1}, \dots, x_{k,t-1}]'$, $\beta \in \mathbb{R}^{(k+1)}$ is an unknown vector of parameters with $\beta = [\beta_0, \beta_1, \dots, \beta_k]'$ and

$$\varepsilon_t | X \sim F_t(\cdot | X), \quad (2.2)$$

where $F_t(\cdot | X)$ is an unknown conditional distribution function and $X = [\mathbf{x}'_0, \dots, \mathbf{x}'_{T-1}]'$ is an $T \times (k+1)$ information matrix.

Let $\{Z_t, \mathcal{F}_t\}_{t=1,2,\dots}$ be an adapted stochastic sequence, such that \mathcal{F}_t is a σ -field in Ω , $\mathcal{F}_s \subseteq \mathcal{F}_t$ for $s < t$, $\sigma(Z_1, \dots, Z_t) \subset \mathcal{F}_t$, where $\sigma(Z_1, \dots, Z_t)$ is the σ -field generated by Z_1, \dots, Z_t . In the context of general forms of serial (nonlinear) dependence, an assumption commonly imposed on the error terms $\{\varepsilon_t, t = 1, 2, \dots\}$ is that the error process is a martingale difference sequence (MDS hereafter) with respect to $\mathcal{F}_t = \sigma(Z_1, \dots, Z_t)$ for $t = 1, 2, \dots$, - i.e. $\mathbb{E}\{\varepsilon_t | \mathcal{F}_{t-1}\} = 0, \quad \forall t \geq 1$. We follow Coudin and Dufour (2009) by departing from this assumption and considering the median as an alternative measure of central tendency. This implies imposing a median-based analogue of the MDS on the error process - namely, we extend the *quantilegale* assumption proposed by Linton and Whang (2007) and suppose that ε_t is a strict conditional mediangale as defined as follows

Definition 1 Let $S(\varepsilon, \mathcal{F}) = \{\varepsilon_t, \mathcal{F}_t\}_{t=1,2,\dots}$ be an adapted stochastic sequence, where $\mathcal{F}_{t-1} = \sigma(\varepsilon_1, \dots, \varepsilon_t, X)$. Then ε_t in $S(\varepsilon, \mathcal{F})$ is a strict conditional mediangale if

$$P[\varepsilon_t > 0 \mid \varepsilon_{t-1}, X] = P[\varepsilon_t < 0 \mid \varepsilon_{t-1}, X] = \frac{1}{2}, \quad (2.3)$$

with

$$\varepsilon_0 = \{\emptyset\}, \quad \varepsilon_{t-1} = \{\varepsilon_1, \dots, \varepsilon_{t-1}\}, \quad \text{for } t \geq 2.$$

Before proceeding further, it is important to emphasize that [Linton and Whang \(2007\)](#) define ε_t as a mediangale if and only if $\mathbb{E} \left[\psi_{\frac{1}{2}}(\varepsilon_t) \mid \mathcal{F}_{t-1} \right] = 0, \quad \forall t$, with $\mathcal{F}_{t-1} = \sigma(\varepsilon_{t-1}, \varepsilon_{t-2}, \dots)$ and $\psi_{\frac{1}{2}}(x) = \mathbb{1}_{[0, \infty)}$. However, note that the strict conditional mediangale assumption (2.3), is conditioned on the entire process X . [Coudin and Dufour \(2009\)](#) argue that as long as the x_t 's are strictly exogenous, the conditional mediangale assumption is analogous to MDS on the signs with respect to $\mathcal{F}_t = \sigma(Z_1, \dots, Z_t)$. However, as the errors of the predictive regressions of the form (2.1) are contemporaneously correlated with the disturbances of the regressors, say u_t , there is feedback from u_t to x_t through ε_t and the process x_t is weakly exogenous, which subsequently suggests that (2.3) can be substituted with

$$P[\varepsilon_t > 0 \mid \varepsilon_{t-1}, \mathcal{X}_{t-1}] = P[\varepsilon_t < 0 \mid \varepsilon_{t-1}, \mathcal{X}_{t-1}] = \frac{1}{2}, \quad (2.4)$$

where $\mathcal{X}_{t-1} = \{x_0, \dots, x_{t-1}\}$. Additionally, assumption (2.3) entails that $\varepsilon_t \mid X$ has no mass at zero for all t , which is only true if $\varepsilon_t \mid X$ is continuous. Following Definition 2.1 of [Coudin and Dufour \(2009\)](#), the strict conditional mediangale assumption can be relaxed, by substituting $P[\varepsilon_t > 0 \mid \varepsilon_{t-1}, X] = P[\varepsilon_t < 0 \mid \varepsilon_{t-1}, X]$ in equation (2.3), which in turn allows ε_t to have discrete distribution, with a non-zero probability mass at zero. In this case, [Coudin and Dufour \(2009\)](#) show that the sign transformation $\mathcal{S}(x, U) = s(x) + [1 - s(x)^2]s(U - 0.5)$ for $U \sim \mathcal{U}(0, 1)$, and as long as U and ε_t are independent, conforms to

$$P[\mathcal{S}(\varepsilon_t, U_t) = 1] = P[\mathcal{S}(\varepsilon_t, U_t) = 0] = \frac{1}{2}, \quad (2.5)$$

irrespective of the distribution of ε_t . However, for the simplicity of exposition, we only consider continuous distributions.

Equation (2.1) in conjunction with assumption (2.3) allows the error terms to possess asymmetric, heteroskedastic and serially (nonlinear) dependent distributions, so long as the conditional medians are zero. Assumption 2.3 allows for many dependent schemes, such as those of the form $\varepsilon_1 = \sigma_1(x_0, \dots, x_{t-2})\epsilon_1$, $\varepsilon_t = \sigma_t(x_0, \dots, x_{t-2}, \varepsilon_1, \dots, \varepsilon_{t-1})\epsilon_t$, $t = 2, \dots, T$, where $\epsilon_1, \dots, \epsilon_T$ are independent with a zero median. In time-series context this includes models such as ARCH, GARCH or stochastic

volatility with non-Gaussian errors. Furthermore, in the mediangale framework the disturbances need not be second order stationary.

Finally, we reiterate [Coudin and Dufour \(2009\)](#) by noting that modifying assumption (2.3) to $P[\varepsilon_t < 0 \mid \mathcal{F}_{t-1}]$ allows us to consider other quantiles.

3 POS tests in linear and nonlinear predictive regressions

In this Section, we derive POS-based tests in the context of linear and nonlinear predictive regressions. First, we divert our attention to the problem of testing the null hypothesis of unpredictability in a linear model, which is later generalized to testing unpredictability in a nonlinear model. Although the former problem is a special case of the latter, for simplicity of exposition the linear predictive regression model is considered first.

3.1 Testing (un)predictability in linear models

Testing the null hypothesis of unpredictability in model (2.1) is equivalent to testing

$$H_0 : \beta = \mathbf{0} \tag{3.1}$$

against the alternative H_1

$$H_1 : \beta = \beta_1. \tag{3.2}$$

where $\mathbf{0}$ is a $(k+1) \times 1$ zero vector. We define the following vector of signs

$$U(T) = (s(y_1), \dots, s(y_T))', \tag{3.3}$$

where, for $1 \leq t \leq T$,

$$s(y_t) = \begin{cases} 1, & \text{if } y_t \geq 0 \\ 0, & \text{if } y_t < 0 \end{cases} \tag{3.4}$$

The test is Neyman-Pearson type test based on signs [see [Lehmann and Romano \(2006\)](#)] which maximize the power function under the constraint $P[\text{reject } H_0 \mid H_0] \leq \alpha$. The idea is to build point-optimal sign-based tests to test the null hypothesis (3.1) against the alternative hypothesis (3.2). To do so, we first define the likelihood function of sample in terms of signs $s(y_1), \dots, s(y_T)$ conditional on X

$$L(U(T), \beta, X) = P[s(y_1) = s_1, \dots, s(y_T) = s_T \mid X] = \prod_{t=1}^T P[s(y_t) = s_t \mid \mathbb{S}_{t-1}, X], \tag{3.5}$$

with

$$\mathbb{S}_0 = \{\emptyset\}, \quad \mathbb{S}_{t-1} = \{s(y_1) = s_1, \dots, s(y_{t-1}) = s_{t-1}\}, \text{ for } t \geq 2, \quad (3.6)$$

and

$$P[s(y_1) = s_1 \mid \mathbb{S}_0, X] = P[s(y_1) = s_1 \mid X], \quad (3.7)$$

where each s_t , for $1 \leq t \leq T$, takes two possible values 0 and 1.

Theorem 1 *Under model (2.1) and assumption (2.3), the variables $s(\varepsilon_1), \dots, s(\varepsilon_T)$, and subsequently $s(y_1), \dots, s(y_T)$ under the null hypothesis of unpredictability, are i.i.d conditional on X according to the distribution*

$$P[s(\varepsilon_1) = 1 \mid X] = P[s(\varepsilon_1) = 0 \mid X] = \frac{1}{2}, \quad t = 1, \dots, T. \quad (3.8)$$

This result holds true iff for any combination of $t = 1, \dots, T$ there is a permutation $\pi : i \rightarrow j$ such that the mediangale assumption holds for j . Then the signs $s(\varepsilon_1), \dots, s(\varepsilon_T)$ are i.i.d.

As the errors satisfy the strict conditional mediangale assumption (2.3), the distribution of the signs $s(\varepsilon_1), \dots, s(\varepsilon_T)$, and in turn $s(y_1), \dots, s(y_T)$ under the null hypothesis of unpredictability, is well-specified, and the signs are mutually independent [see [Coudin and Dufour \(2009\)](#)]. However, note that under the alternative hypothesis, the strict conditional mediangale assumption no longer holds. Thus, a sign-based test for testing the null hypothesis (3.1) against the alternative hypothesis (3.2) is given by the following proposition:

Proposition 1 *Under assumptions (2.1) and (2.3), let H_0 and H_1 be defined by (3.1) - (3.2),*

$$SL_T(\beta_1) = \sum_{t=1}^T a_t(\beta_1)s(y_t), \quad (3.9)$$

where, for $t = 1, \dots, T$,

$$a_t(\beta_1) = \ln \left\{ \frac{P[y_t \geq 0 \mid \underline{S}_{t-1}, X]}{P[y_t < 0 \mid \underline{S}_{t-1}, X]} \right\}, \quad (3.10)$$

and suppose the constant $c_1(\beta_1)$ satisfies $P\left[\sum_{t=1}^T a_t(\beta_1)s(y_t) > c_1(\beta_1)\right] = \alpha$ under H_0 , with $0 < \alpha < 1$. Then the test that rejects H_0 when

$$SL_T(\beta_1) > c_1(\beta_1) \quad (3.11)$$

is most powerful (conditional on X) for testing H_0 against H_1 among level- α tests based on the signs $(s(y_1), \dots, s(y_T))'$.

Notice that the calculation of the test statistic $SL_T(\beta_1)$ depends on the weights $a_t(\beta_1)$, which in turn depend on the calculation of the conditional probabilities $P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]$ and $P[y_t < 0 \mid \mathbb{S}_{t-1}, X]$. The latter two terms involve the distribution of the joint process of signs $(s(y_1), \dots, s(y_T))'$ conditional on X , which is unknown. An alternative way to compute the terms $P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]$ and $P[y_t < 0 \mid \mathbb{S}_{t-1}, X]$ is to use simulations, however, this will be computationally burdensome as it requires the simulation of the joint distribution of the process of signs $(s(y_1), \dots, s(y_T))'$ conditional on X , which depends on the sample size T . Hence, to propose a feasible test statistic, say $\widetilde{SL}_T(\beta_1)$, we impose the following assumption.

Assumption A1: *Under the alternative hypothesis, the sign process $\{s(y_t)\}_{t=0}^\infty$ conditional on X follows a Markov process.*

Now, under assumption **A1**, the probability terms $P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]$ and $P[y_t < 0 \mid \mathbb{S}_{t-1}, X]$ in the weight function $a_t(\beta_1)$ can be expressed as follows:

$$\begin{cases} P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X] = P[y_t \geq 0 \mid y_{t-1} \geq 0, X]^{s(y_{t-1})} P[y_t \geq 0 \mid y_{t-1} < 0, X]^{1-s(y_{t-1})}, \\ P[y_t < 0 \mid \mathbb{S}_{t-1}, X] = P[y_t < 0 \mid y_{t-1} \geq 0, X]^{s(y_{t-1})} P[y_t < 0 \mid y_{t-1} < 0, X]^{1-s(y_{t-1})}. \end{cases} \quad (3.12)$$

Under this assumption, expressions $P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]$ and $P[y_t < 0 \mid \mathbb{S}_{t-1}, X]$ simplify the calculation of the test statistic $SL_T(\beta_1)$ and lead to the following result:

Corollary 1 *Under assumptions (2.1) and (2.3), let H_0 and H_1 be defined by (3.1) - (3.2),*

$$\widetilde{SL}_T(\beta_1) = \sum_{t=1}^T \tilde{a}_t(\beta_1) s(y_t) + \sum_{t=1}^T \tilde{b}_t(\beta_1) s(y_t) s(y_{t-1}), \quad (3.13)$$

such that

$$\tilde{a}_1(\beta_1) = \ln \left\{ \frac{\pi_1^c(\beta_1)}{\pi_1(\beta_1)} \right\}, \quad \tilde{b}_1(\beta_1) = 0, \quad (3.14)$$

and for $t = 2, \dots, T$,

$$\tilde{a}_t(\beta_1) = \ln \left\{ \left(1 - \frac{\pi_{t,t-1}(\beta_1)}{\pi_{t-1}(\beta_1)} \right) \middle/ \frac{\pi_{t,t-1}(\beta_1)}{\pi_{t-1}(\beta_1)} \right\}, \quad \tilde{b}_t(\beta_1) = \ln \left\{ \frac{1 - \left(\frac{\pi_t(\beta_1)}{\pi_{t-1}^c(\beta_1)} - \frac{\pi_{t,t-1}(\beta_1)}{\pi_{t-1}(\beta_1)} \right)}{\frac{\pi_t(\beta_1)}{\pi_{t-1}^c(\beta_1)} - \frac{\pi_{t,t-1}(\beta_1)}{\pi_{t-1}(\beta_1)}} \right\} - \tilde{a}_t(\beta_1), \quad (3.15)$$

where for $t = 2, \dots, T$

$$\pi_t(\beta_1) = P[\varepsilon_t < -\beta_1' \mathbf{x}_{t-1} \mid X] \quad (3.16)$$

$$\pi_{t,t-1}(\beta_1) = P[\varepsilon_t < -\beta_1' \mathbf{x}_{t-1}, \varepsilon_{t-1} < -\beta_1' \mathbf{x}_{t-2} \mid X] \quad (3.17)$$

$$\pi_t^c(\beta_1) = 1 - \pi_t(\beta_1), \quad (3.18)$$

noting that $\pi_{1,0} = \pi_1 = P[\varepsilon_1 < -\beta_1' \mathbf{x}_0 \mid X]$. Further, suppose the constant $\tilde{c}_1(\beta_1)$ satisfies

$$P\left[\sum_{t=1}^T \tilde{a}_t(\beta_1)s(y_t) + \sum_{t=1}^T \tilde{b}_t(\beta_1)s(y_t)s(y_{t-1}) > \tilde{c}_1(\beta_1) \mid H_0\right] = \alpha \quad (3.19)$$

with $0 < \alpha < 1$. Then the test that rejects H_0 when

$$\widetilde{S}L_T(\beta_1) > \tilde{c}_1(\beta_1) \quad (3.20)$$

is most powerful (conditional on X) for testing H_0 against H_1 among level- α tests based on the signs $(s(y_1), \dots, s(y_T))'$.

Now the calculation of the test statistic $\widetilde{S}L_T(\beta_1)$ depends on the univariate and bivariate conditional probabilities $P[\varepsilon_t < \cdot \mid X]$ and $P[\varepsilon_{t-1} < \cdot, \varepsilon_t < \cdot \mid X]$.

Observe that under the null hypothesis of unpredictability, the signs $s(y_1), \dots, s(y_T)$ are i.i.d. according to a Bernoulli $\text{Bin}(1, 0.5)$. Therefore, under the null hypothesis, the distribution of the test statistic $\widetilde{S}L_T(\beta_1)$ only depends on the known weights $\tilde{a}_t(\beta_1)$ and $\tilde{b}_t(\beta_1)$ and does not involve any nuisance parameters. Nonparametric assumption (2.3) implies that tests based on $\widetilde{S}L_T(\beta_1)$, such as the test given by (3.20), are distribution-free and robust against heteroskedasticity of unknown form, and thus, a nonparametric *pivotal function*. Under the alternative hypothesis, however, the power function of the test depends on the form of the bivariate and the marginal distributions of the error terms respectively.

One approach for calculating these probabilities entails fitting copula models, which provide the means of separating the marginal distributions of the process from their respective dependence structure. The latter stems from Sklar (1959), which decomposes the joint distribution of $\mathbf{Y} = [y_1, \dots, y_T]'$ conditional on X as

$$\mathbf{Y} \mid X \sim H(\cdot \mid X) = C(F_1(\cdot \mid X), \dots, F_T(\cdot \mid X)), \quad (3.21)$$

where $F_t(\cdot \mid X)$ for $t = 1, \dots, T$ are uniformly distributed marginals - i.e. $F_t(\cdot \mid X) := u_t \sim U[0, 1]$. In our context the elements of \mathbf{Y} are uncorrelated, yet exhibit serial nonlinear dependence which is captured by the copula function $C(\cdot)$. The implication of this for specifying a copula function for the

joint distribution of \mathbf{Y} conditional on X is imposing an identity correlation matrix. We may consider the “jointly symmetric” copulas proposed by [Oh and Patton \(2016\)](#), which can be constructed with any given (possibly asymmetric) copula family. In addition, when they are combined with symmetric marginals, they ensure an identity correlation matrix. A “jointly symmetric” copula is defined as follows:

Definition 2 *The n dimensional copula C^{JS} , is jointly symmetric:*

$$C^{JS}(u_1, \dots, u_n) = \frac{1}{2^n} \sum_{k_1=0}^2 \cdots \sum_{k_n=0}^2 (-1)^R C(\tilde{u}_1, \dots, \tilde{u}_i, \dots, \tilde{u}_n), \quad (3.22)$$

$$\text{where } R = \sum_{i=1}^n \mathbf{1}\{k_i = 2\}, \quad \text{and} \quad \tilde{u}_i = \begin{cases} 1, & k_i = 0 \\ u_i, & k_i = 1 \\ 1 - u_i, & k_i = 2 \end{cases} \quad (3.23)$$

The general idea is that the average of mirror image rotations of a possibly asymmetric copula along each axis generates a jointly symmetric copula [see [Oh and Patton \(2016\)](#)]. For instance, the marginals can be assumed to possess standard normal distributions, while the nonlinear dependency is modeled using jointly symmetric copulas.

In the literature, the means of allowing for nonlinear serial dependence for processes which are linearly unrelated is often accompanied by the assumption that \mathbf{Y} conditional on X is distributed according to a multivariate Student’s t distribution - i.e. $\mathbf{Y} \mid X \sim \mathbf{t}_\nu(\mathbf{0}, I)$, where $\mathbf{0}$ is a zero vector corresponding to the location parameter, and I is an identity matrix. When I is imposed on the multivariate Student’s t distribution, the conditional joint distribution of \mathbf{Y} does not factorize into the product of its marginals. Thus, a special case we may consider consists in $\varepsilon_1, \varepsilon_2, \dots, \varepsilon_{T-1}, \varepsilon_T$ distributed according to Student’s t distribution $t(\nu)$, with ν degrees of freedom. We may evaluate the bivariate probabilities $P[\varepsilon_{t-1} < \cdot, \varepsilon_t < \cdot \mid X]$ using a multivariate Student’s t distribution $\mathbf{t}_\nu(\mathbf{0}, I)$, by imposing a zero location parameter vector and the identity correlation matrix I . Then the probabilities (3.16), (3.17) and (3.18) are evaluated as follows:

$$\pi_t(\beta_1) = \tau_\nu(-\beta_1' \mathbf{x}_{t-1}) \quad (3.24)$$

$$\pi_{t,t-1}(\beta_1) = \mathcal{T}_\nu(-\beta_1' \mathbf{x}_{t-1}, -\beta_1' \mathbf{x}_{t-2}) \quad (3.25)$$

$$\pi_t^c(\beta_1) = 1 - \pi_t(\beta_1), \quad (3.26)$$

where $\tau_\nu(\cdot)$ is the Student’s t distribution function with ν degrees of freedom, $\mathcal{T}_\nu(\cdot, \cdot)$ is the bivariate t distribution with ν degrees of freedom, and with location and shape parameters $\mathbf{0}$ and I respectively.

3.2 Monte Carlo tests

We may obtain exact critical values and confidence intervals in finite samples whose distribution is intractable by simulations using Monte Carlo test techniques [see [Dwass \(1957\)](#), [Barnard \(1963\)](#), [Dufour \(2006\)](#), [Coudin and Dufour \(2009\)](#)]. Under the null hypothesis of unpredictability, the distribution of the test statistic, $\widetilde{SL}_T(\beta_1)$, does not involve any nuisance parameters and is a pivotal function. As such, performing Monte Carlo tests is rather straightforward¹. Hence, the distribution of $\widetilde{SL}_T(\beta_1)$, can be simulated under the null hypothesis and the relevant critical values can be evaluated to any degree of precision with a sufficient number of replications. Since the test statistic $\widetilde{SL}_T(\beta_1)$ is a continuous random variable, its quantiles $F^{-1}(\alpha)$ are easy to compute, where for any probability distribution $F(x)$ the quantile function is defined as follows:

$$F^{-1}(\alpha) = \begin{cases} \inf\{x : F(x) \geq \alpha\} & \text{if } 0 < \alpha < 1 \\ \inf\{x : F(x) > 0\} & \text{if } \alpha = 0 \\ \sup\{x : F(x) < 1\} & \text{if } \alpha = 1. \end{cases} \quad (3.27)$$

To simulate the distribution of $\widetilde{SL}_T(\beta_1)$, the following algorithm is implemented:

Algorithm 1 Algorithm for utilizing the POS-based tests (continuous ε_t)

- 1: Compute $\widetilde{SL}_T^0(\beta_1) \leftarrow \widetilde{SL}_T(\beta_1)$ based on the observed data;
 - 2: Choose B such that $\alpha(B+1) \in \mathbb{N}$;
 - 3: **for** j in $1 : B$ **do**
 - 4: Generate $\{s_t^{(j)}\}_{t=1}^T$, s.t. $s_t^{(j)} \sim \text{Bin}(n=1, p=0.5)$;
 - 5: Compute $\widetilde{SL}_T^{(j)}(\beta_1)$ using the generated sample;
 - 6: **end for**
 - 7: Compute $\tilde{c}_1(\beta_1) \leftarrow (1-\alpha)\%$ quantile of $\{\widetilde{SL}_T^{(j)}(\beta_1)\}_{j=1}^B$;
 - 8: **if** $\widetilde{SL}_T^0(\beta_1) \geq \tilde{c}_1(\beta_1)$ **then**
 - 9: Reject H_0
 - 10: **end if**
-

As discussed in Section 2, suppose the errors ε_t possess a discrete distribution, and the test-statistic is subsequently modified to reflect this. Then $\widetilde{SL}_T(\beta_1)$ is no longer continuous, such that for the replications $\widetilde{SL}_T^{(1)}(\beta_1), \dots, \widetilde{SL}_T^{(B)}(\beta_1)$

$$P \left[\widetilde{SL}_T^{(l)}(\beta_1) = \widetilde{SL}_T^{(m)}(\beta_1) \right] \neq 0, \quad \text{for } l \neq m \quad \text{and} \quad i, j = 1, \dots, B, \quad (3.28)$$

and Monte Carlo tests with randomized tie-breaking approach suggested by [Dufour \(2006\)](#) and [Coudin](#)

¹[Dufour \(2006\)](#) consider extensions involving nuisance parameters using maximized Monte Carlo tests (MMC).

and Dufour (2009) may be used to perform hypothesis tests. The latter entails “breaking” ties according to a uniform distribution. In other words, for each variable $\widetilde{S}L_T^{(j)}(\beta_1), j = 1, \dots, B$, we introduce a random variable $W^{(j)}, j = 1, \dots, B$, where $W^{(j)} \sim \mathcal{U}(0, 1)$, such that $W(B) = (W^{(1)}, \dots, W^{(B)})'$ is independent of $S(B) = (\widetilde{S}L_T^{(1)}(\beta_1), \dots, \widetilde{S}L_T^{(B)}(\beta_1))'$. Then we consider the pairs $(\widetilde{S}L_T^{(j)}(\beta_1), W^{(j)}), j = 1, \dots, B$, ordered lexicographically - i.e.,

$$\begin{aligned} \left(\widetilde{S}L_T^{(n)}(\beta_1), W^{(n)} \right) \geq \left(\widetilde{S}L_T^{(m)}(\beta_1), W^{(m)} \right) \Leftrightarrow \\ \left\{ \widetilde{S}L_T^{(n)}(\beta_1) > \widetilde{S}L_T^{(m)}(\beta_1) \quad \text{or} \quad \left(\widetilde{S}L_T^{(n)}(\beta_1) = \widetilde{S}L_T^{(m)}(\beta_1) \quad \text{and} \quad W^{(n)} \geq W^{(m)} \right) \right\} \end{aligned} \quad (3.29)$$

where using the indicator and Kronecker delta functions,

$$\begin{aligned} \mathbb{1} \left[\left(\widetilde{S}L_T^{(n)}(\beta_1), W^{(n)} \right) \geq \left(\widetilde{S}L_T^{(m)}(\beta_1), W^{(m)} \right) \right] = \\ \mathbb{1} \left[\widetilde{S}L_T^{(n)}(\beta_1) > \widetilde{S}L_T^{(m)}(\beta_1) \right] + \delta \left(\widetilde{S}L_T^{(n)}(\beta_1) - \widetilde{S}L_T^{(m)}(\beta_1) \right) \mathbb{1} \left[W^{(n)} \geq W^{(m)} \right]. \end{aligned} \quad (3.30)$$

and thus according to (3.30), $\widetilde{S}L_T^{(1)}(\beta_1), \dots, \widetilde{S}L_T^{(B)}(\beta_1)$ is ordered as the pairs $(\widetilde{S}L_T^{(j)}(\beta_1), W^{(j)}), j = 1, \dots, B$. The algorithm for the latter is as follows:

Algorithm 2 Algorithm for utilizing the POS-based tests (discrete ε_t)

- 1: Compute $\widetilde{S}L_T^0(\beta_1) \leftarrow \widetilde{S}L_T(\beta_1)$ based on the observed data;
 - 2: Choose B such that $\alpha(B+1) \in \mathbb{N}$;
 - 3: **for** j in $1 : B$ **do**
 - 4: Generate $\{\mathcal{S}_t^{(j)}\}_{t=1}^T$, s.t. $\mathcal{S}_t^{(j)} \sim \text{Bin}(n=1, p=0.5)$;
 - 5: Compute $\widetilde{S}L_T^{(j)}(\beta_1)$ using the generated sample;
 - 6: Generate $W^{(j)} \sim \mathcal{U}(0, 1)$ to produce the pairs $(\widetilde{S}L_T^{(j)}(\beta_1), W^{(j)})$;
 - 7: **end for**
 - 8: Order the pairs: $(\widetilde{S}L_T^{(n)}(\beta_1), W^{(n)}) \geq (\widetilde{S}L_T^{(m)}(\beta_1), W^{(m)}) \Leftrightarrow$
 $\{\widetilde{S}L_T^{(n)}(\beta_1) > \widetilde{S}L_T^{(m)}(\beta_1) \text{ or } (\widetilde{S}L_T^{(n)}(\beta_1) = \widetilde{S}L_T^{(m)}(\beta_1) \text{ and } W^{(n)} \geq W^{(m)})\}.$
 - 9: Compute $\tilde{c}_1(\beta_1) \leftarrow (1 - \alpha)\%$ quantile of $\{\widetilde{S}L_T^{(j)}(\beta_1)\}_{j=1}^B$;
 - 10: **if** $\widetilde{S}L_T^0(\beta_1) \geq \tilde{c}_1(\beta_1)$ **then**
 - 11: Reject H_0
 - 12: **end if**
-

3.3 Testing general full coefficient hypotheses in nonlinear predictive regressions

Following Dufour and Taamouti (2010), we may extend the earlier results by considering a nonlinear

predictive regression model of the form

$$y_t = f(\mathbf{x}_{t-1}, \boldsymbol{\beta}) + \varepsilon_t, \quad t = 1, \dots, T, \quad (3.31)$$

where \mathbf{x}_{t-1} is an observable $(k+1) \times 1$ vector of stochastic explanatory variables, such that $\mathbf{x}_{t-1} = [1, x_{1,t-1}, \dots, x_{k,t-1}]'$, $f(\cdot)$ is a scalar function, $\boldsymbol{\beta} \in \mathbb{R}^{(k+1)}$ is an unknown vector of parameters and

$$\varepsilon_t \mid X \sim F_t(\cdot \mid X), \quad (3.32)$$

where as before $F_t(\cdot \mid X)$ is a distribution function and $X = [\mathbf{x}'_0, \dots, \mathbf{x}'_{T-1}]'$ is an $T \times (k+1)$ matrix. Once again, we suppose that the error terms process $\{\varepsilon_t, t = 1, 2, \dots\}$ is a strict conditional mediangale, such that

$$P[\varepsilon_t > 0 \mid \boldsymbol{\varepsilon}_{t-1}, X] = P[\varepsilon_t < 0 \mid \boldsymbol{\varepsilon}_{t-1}, X] = \frac{1}{2}, \quad (3.33)$$

with

$$\boldsymbol{\varepsilon}_0 = \{\emptyset\}, \quad \boldsymbol{\varepsilon}_{t-1} = \{\varepsilon_1, \dots, \varepsilon_{t-1}\}, \quad \text{for } t \geq 2, \quad (3.34)$$

and where (3.33) entails that $\varepsilon_t \mid X$ has no mass at zero, *i.e.* $P[\varepsilon_t = 0 \mid X] = 0$ for all t . We do not require that the parameter vector $\boldsymbol{\beta}$ be identified. We consider testing the null hypothesis

$$H(\boldsymbol{\beta}_0) : \boldsymbol{\beta} = \boldsymbol{\beta}_0 \quad (3.35)$$

against the alternative hypothesis

$$H(\boldsymbol{\beta}_1) : \boldsymbol{\beta} = \boldsymbol{\beta}_1. \quad (3.36)$$

A test for $H(\boldsymbol{\beta}_0)$ against $H(\boldsymbol{\beta}_1)$ can be constructed as in Section 3.1. First, we note that model (3.31) is equivalent to the transformed model

$$\tilde{y}_t = g(\mathbf{x}_{t-1}, \boldsymbol{\beta}, \boldsymbol{\beta}_0) + \varepsilon_t, \quad (3.37)$$

where $\tilde{y}_t = y_t - f(\mathbf{x}_{t-1}, \boldsymbol{\beta}_0)$ and $g(\mathbf{x}_{t-1}, \boldsymbol{\beta}, \boldsymbol{\beta}_0) = f(\mathbf{x}_{t-1}, \boldsymbol{\beta}) - f(\mathbf{x}_{t-1}, \boldsymbol{\beta}_0)$. Thus, testing $H(\boldsymbol{\beta}_0)$ against $H(\boldsymbol{\beta}_1)$ is equivalent to testing

$$\bar{H}_0 : g(\mathbf{x}_{t-1}, \boldsymbol{\beta}, \boldsymbol{\beta}_0) = \mathbf{0}, \quad \text{for } t = 1, \dots, T, \quad (3.38)$$

against

$$\bar{H}_1 : g(\mathbf{x}_{t-1}, \boldsymbol{\beta}, \boldsymbol{\beta}_0) = f(\mathbf{x}_{t-1}, \boldsymbol{\beta}_1) - f(\mathbf{x}_{t-1}, \boldsymbol{\beta}_0), \quad \text{for } t = 1, \dots, T. \quad (3.39)$$

For $\tilde{U}(T) = (s(\tilde{y}_1), \dots, s(\tilde{y}_T))'$, where, for $1 \leq t \leq T$,

$$s(\tilde{y}_t) = \begin{cases} 1, & \text{if } \tilde{y}_t \geq 0 \\ 0, & \text{if } \tilde{y}_t < 0 \end{cases} \quad (3.40)$$

the likelihood function of new random sample $\{s(\tilde{y}_t)\}_{t=1}^T$ conditional on X is given by:

$$L(\tilde{U}(T), \boldsymbol{\beta}, X) = P[s(\tilde{y}_1) = \tilde{s}_1, \dots, s(\tilde{y}_T) = \tilde{s}_T \mid X] = \prod_{t=1}^T P[s(\tilde{y}_t) = \tilde{s}_t \mid \tilde{S}_{t-1}, X], \quad (3.41)$$

with

$$\tilde{S}_0 = \{\emptyset\}, \quad \tilde{S}_{t-1} = \{s(\tilde{y}_1) = \tilde{s}_1, \dots, s(\tilde{y}_{t-1}) = \tilde{s}_{t-1}\}, \quad \text{for } t \geq 2, \quad (3.42)$$

and

$$P[s(\tilde{y}_1) = \tilde{s}_1 \mid \tilde{S}_0, X] = P[s(\tilde{y}_1) = \tilde{s}_1 \mid X], \quad (3.43)$$

where each \tilde{s}_t , for $1 \leq t \leq T$, takes two possible values 0 and 1. Thus, we can use the result of Proposition 1 to derive a sign-based test to test the null hypothesis (3.35) against the alternative hypothesis (3.36), which leads to the following proposition:

Proposition 2 Under assumptions (3.31) and (3.33), let $H(\boldsymbol{\beta}_0)$ and $H(\boldsymbol{\beta}_1)$ be defined by (3.35) - (3.36),

$$SN_T(\boldsymbol{\beta}_0 \mid \boldsymbol{\beta}_1) = \sum_{t=1}^T a_t(\boldsymbol{\beta}_0 \mid \boldsymbol{\beta}_1) s(y_t - f(\mathbf{x}_{t-1}, \boldsymbol{\beta}_0)) \quad (3.44)$$

where, for $t = 1, \dots, T$,

$$a_t(\boldsymbol{\beta}_0 \mid \boldsymbol{\beta}_1) = \ln \left\{ \frac{P[\tilde{y}_t \geq 0 \mid \tilde{S}_{t-1}, X]}{P[\tilde{y}_t < 0 \mid \tilde{S}_{t-1}, X]} \right\}, \quad (3.45)$$

and suppose the constant $c_1(\boldsymbol{\beta}_0, \boldsymbol{\beta}_1)$ satisfies $P\left[\sum_{t=1}^T a_t(\boldsymbol{\beta}_0 \mid \boldsymbol{\beta}_1) s(y_t - f(\mathbf{x}_{t-1}, \boldsymbol{\beta}_0)) > c_1(\boldsymbol{\beta}_0, \boldsymbol{\beta}_1)\right] = \alpha$ under $H(\boldsymbol{\beta}_0)$, with $0 < \alpha < 1$. Then the test that rejects $H(\boldsymbol{\beta}_0)$ when

$$SN_T(\boldsymbol{\beta}_0 \mid \boldsymbol{\beta}_1) > c_1(\boldsymbol{\beta}_0, \boldsymbol{\beta}_1) \quad (3.46)$$

is most powerful (conditional on X) for testing $H(\boldsymbol{\beta}_0)$ against $H(\boldsymbol{\beta}_1)$ among level- α tests based on the signs $(s(\tilde{y}_1), \dots, s(\tilde{y}_T))'$.

As in Section 3.1, the calculation of the weights $a_t(\beta_0 \mid \beta_1)$, which depend on the terms $P[\tilde{y}_t \geq 0 \mid \mathbb{S}_{t-1}, X]$ and $P[\tilde{y}_t < 0 \mid \mathbb{S}_{t-1}, X]$, is made feasible by considering assumption **A1** which extends to the process $\{s(\tilde{y}_t), t = 0, 1, \dots\}$. Thus, under the alternative hypothesis, the sign process $\{s(\tilde{y}_t)\}_{t=0}^\infty$ is a Markov process, which leads to the following Corollary:

Corollary 2 *Under assumptions (2.1) and (2.3), let $H(\beta_0)$ and $H(\beta_1)$ be defined by (3.35) - (3.36),*

$$\widehat{SN}_T(\beta_0 \mid \beta_1) = \sum_{t=1}^T \tilde{a}_t(\beta_0 \mid \beta_1) s(\tilde{y}_t) + \sum_{t=1}^T \tilde{b}_t(\beta_0 \mid \beta_1) s(\tilde{y}_t) s(\tilde{y}_{t-1}), \quad (3.47)$$

such that

$$\tilde{a}_1(\beta_0 \mid \beta_1) = \ln \left\{ \frac{\tilde{\pi}_t^c(\beta_1)}{\tilde{\pi}_t(\beta_1)} \right\}, \quad \tilde{b}_1(\beta_0 \mid \beta_1) = 0, \quad (3.48)$$

and for $t = 2, \dots, T$,

$$\tilde{a}_t(\beta_0 \mid \beta_1) = \ln \left\{ \left(1 - \frac{\tilde{\pi}_{t,t-1}(\beta_1)}{\tilde{\pi}_{t-1}(\beta_1)} \right) \middle/ \frac{\tilde{\pi}_{t,t-1}(\beta_1)}{\tilde{\pi}_{t-1}(\beta_1)} \right\}, \quad (3.49)$$

$$\tilde{b}_t(\beta_0 \mid \beta_1) = \ln \left\{ \frac{1 - \left(\frac{\tilde{\pi}_t(\beta_1)}{\tilde{\pi}_{t-1}^c(\beta_1)} - \frac{\tilde{\pi}_{t,t-1}(\beta_1)}{\tilde{\pi}_{t-1}^c(\beta_1)} \right)}{\frac{\tilde{\pi}_t(\beta_1)}{\tilde{\pi}_{t-1}^c(\beta_1)} - \frac{\tilde{\pi}_{t,t-1}(\beta_1)}{\tilde{\pi}_{t-1}^c(\beta_1)}} \right\} - \tilde{a}_t(\beta_0 \mid \beta_1) \quad (3.50)$$

where for $t = 2, \dots, T$

$$\tilde{\pi}_t(\beta_1) = P[\varepsilon_t < f(\mathbf{x}_{t-1}, \beta_0) - f(\mathbf{x}_{t-1}, \beta_1) \mid X] \quad (3.51)$$

$$\tilde{\pi}_{t,t-1}(\beta_1) = P[\varepsilon_t < f(\mathbf{x}_{t-1}, \beta_0) - f(\mathbf{x}_{t-1}, \beta_1), \varepsilon_{t-1} < f(\mathbf{x}_{t-2}, \beta_0) - f(\mathbf{x}_{t-2}, \beta_1) \mid X] \quad (3.52)$$

$$\tilde{\pi}_t^c(\beta_1) = 1 - \tilde{\pi}_t(\beta_1), \quad (3.53)$$

noting that $\tilde{\pi}_{1,0} = \tilde{\pi}_1 = P[\varepsilon_1 < f(\mathbf{x}_{0-1}, \beta_0) - f(\mathbf{x}_{0-1}, \beta_1) \mid X]$. Further suppose the constant $\tilde{c}_1(\beta_0, \beta_1)$ satisfies

$$P[\widehat{SN}_T(\beta_0 \mid \beta_1) > \tilde{c}_1(\beta_0, \beta_1) \mid H(\beta_0)] = \alpha \quad (3.54)$$

with $0 < \alpha < 1$. Then the test that rejects $H(\beta_0)$ when

$$\widehat{SN}_T(\beta_0 \mid \beta_1) > \tilde{c}_1(\beta_0, \beta_1) \quad (3.55)$$

is most powerful (conditional on X) for testing $H(\beta_0)$ against $H(\beta_1)$ among level- α tests based on the signs $(s(\tilde{y}_1), \dots, s(\tilde{y}_T))'$.

A special case entails considering a linear function $f(\mathbf{x}_{t-1}, \beta) = \beta' \mathbf{x}_{t-1}$, where as before we may

suppose that ε_t for $t = 1, \dots, T$ are distributed according to Student's t distribution $t(\nu)$, with ν degrees of freedom, and where the bivariate probabilities can be calculated by imposing a bivariate Student's t distribution $\mathbf{t}_\nu(\mathbf{0}, I)$, with a zero location parameter and identity matrix to capture the serial (nonlinear) dependence. Then the statistic for testing the null hypothesis $H(\beta_0)$ against the alternative $H(\beta_1)$ is expressed using the weights

$$\tilde{\pi}_t(\beta_1) = \tau_\nu((\beta_1 - \beta_0)' \mathbf{x}_0) \quad (3.56)$$

$$\tilde{\pi}_{t,t-1}(\beta_1) = \mathcal{T}_\nu((\beta_0 - \beta_1)' \mathbf{x}_{t-1}, (\beta_0 - \beta_1)' \mathbf{x}_{t-2}) \quad (3.57)$$

$$\tilde{\pi}_t^c(\beta_1) = 1 - \tilde{\pi}_t(\beta_1), \quad (3.58)$$

where $\tau_\nu(\cdot)$ is the Student's t distribution function with ν degrees of freedom, $\mathcal{T}_\nu(\cdot, \cdot)$ is the bivariate t distribution with ν degrees of freedom, and with location and shape parameters 0 and I respectively.

As in Section 3.1, the test statistic $\widehat{SN}_T(\beta_0 | \beta_1)$ depends on a predetermined alternative hypothesis β_1 , which in practice is unknown. Therefore, in Section 4 we will suggest an adaptive approach based on the split-sample technique [see Dufour and Taamouti (2010)] which can be used to choose an optimal alternative hypothesis at which the power of the test is maximized.

4 Choice of the optimal alternative hypothesis

Point-optimal tests depend on the alternative $\beta = \beta_1$, which in practice is unknown. Formally, the test statistic $\widehat{SN}_T(\beta_0 | \beta_1)$ for testing the full-coefficient hypothesis (3.35) is a function of β_1

$$\widehat{SN}_T(\beta_0 | \beta_1) = \sum_{t=1}^T \tilde{a}_t(\beta_0 | \beta_1) s(y_t - f(\mathbf{x}_{t-1}, \beta_0)) + \sum_{t=1}^T \tilde{b}_t(\beta_0 | \beta_1) s(y_t - f(\mathbf{x}_{t-1}, \beta_0)) s(y_{t-1} - f(\mathbf{x}_{t-2}, \beta_0)), \quad (4.1)$$

which in turn implies that its power function, say $\Pi(\beta_0, \beta_1)$, is also a function of β_1 . Therefore, the choice of the alternative β_1 has a direct impact on its power function. In other words,

$$\Pi(\beta_0, \beta_1) = P[\widehat{SN}_T(\beta_0 | \beta_1) > \tilde{c}_1(\beta_0, \beta_1) | H(\beta_1)], \quad (4.2)$$

where $\tilde{c}_1(\beta_0, \beta_1)$ satisfies the constraint

$$P[\widehat{SN}_T(\beta_0 | \beta_1) > \tilde{c}_1(\beta_0, \beta_1) | H(\beta_0)] \leq \alpha. \quad (4.3)$$

Our objective is to choose the value of β_1 at which the power function of the POS-based test statistic

is maximized and is close to that of the power envelope. This can be accomplished in a number of ways. [Dufour and Taamouti \(2010\)](#) suggest an adaptive approach based on the split-sample technique [see [Dufour and Jasiak \(2001\)](#)] to estimate the optimal alternative and to calculate the test statistic, to make size control easier and maximize power. For a review of adaptive approach for parametric tests with nonstandard distributions see [Dufour and Taamouti \(2003\)](#) and [Dufour et al. \(2008\)](#).

This approach consists in splitting the sample into two independent parts, where the alternative β_1 is estimated using the first part, while the POS-based test statistic $\widehat{SN}_T(\beta_0 | \beta_1)$ is calculated using the second part of the sample and the alternative β_1 that had been estimated using the first subsample. By adopting this technique, size control is easier and the power function of the POS-based test traces out the power envelope. Let $T = T_1 + T_2$, $y = (y'_{(1)}, y'_{(2)})'$, $X = (X'_{(1)}, X'_{(2)})'$, and $\varepsilon = (\varepsilon'_{(1)}, \varepsilon'_{(2)})'$, where $y_{(i)}$, $X_{(i)}$ and $\varepsilon_{(i)}$ for $i \in \{1, 2\}$ each have T_i rows. The first T_1 observations of y and X can thus be denoted by $y_{(1)}$ and $X_{(1)}$, which are used to estimate the alternative hypothesis β_1 . If the function $f(\mathbf{x}_{t-1}, \beta)$ is linear - i.e. $f(\mathbf{x}_{t-1}, \beta) = \beta'_0 \mathbf{x}_{t-1}$, then β_1 can be obtained using the OLS estimator:

$$\hat{\beta}_{(1)} = (X'_{(1)} X_{(1)})^{-1} X'_{(1)} y_{(1)}. \quad (4.4)$$

Alternatively, in the case of extreme observations, other robust estimators that are less sensitive to outliers can be utilized [see [Maronna et al. \(2019\)](#) for a review of robust estimators]. Since $\hat{\beta}_{(1)}$ is independent of $X_{(2)}$, the last T_2 observations can be used to calculate the test statistic and obtain a valid POS-based test

$$\widehat{SN}_T(\beta_0 | \beta_{(1)}) = \sum_{t=T_1+1}^T \tilde{a}_t(\beta_0 | \beta_{(1)}) s(y_t - \mathbf{x}'_{t-1} \beta_0) + \sum_{t=T_1+1}^T \tilde{b}_t(\beta_0 | \beta_{(1)}) s(y_t - \mathbf{x}'_{t-1} \beta_0) s(y_{t-1} - \mathbf{x}'_{t-2} \beta_0), \quad (4.5)$$

When $f(\mathbf{x}_{t-1}, \beta)$ is a nonlinear function of β , we resort to nonlinear least squares or the maximum likelihood estimation method to obtain the alternative hypothesis β_1 . Similar to the linear case, this entails splitting the sample into two independent subsamples T_1 and T_2 , such that $y_{(1)}$ and $X_{(1)}$ correspond to the first subsample T_1 , using which the alternative hypothesis β_1 can be estimated using a nonlinear least squares method

$$\hat{\beta}_{(1)} = \arg \min_{\beta_1} \sum_{t=1}^{T_1} [y_t - f(\mathbf{x}_{t-1}, \beta_1)]^2. \quad (4.6)$$

Similarly, $y_{(2)}$ and $X_{(2)}$ which correspond to the second subsample are used to calculate the test statistic:

$$\widehat{SN}_T(\beta_0 | \beta_{(1)}) = \sum_{t=T_1+1}^T \tilde{a}_t(\beta_0 | \beta_{(1)})s(y_t - f(\mathbf{x}_{t-1}, \beta_0)) \quad (4.7)$$

$$+ \sum_{t=T_1+1}^T \tilde{b}_t(\beta_0 | \beta_{(1)})s(y_t - f(\mathbf{x}_{t-1}, \beta_0))s(y_{t-1} - f(\mathbf{x}_{t-2}, \beta_0)), \quad (4.8)$$

An array of different possibilities exist for choosing the dimensions of the independent subsamples T_1 and T_2 . However, as [Dufour and Taamouti \(2010\)](#) have noted, the number of observations retained in the first and the second subsamples respectively has a direct impact on the power of the test. A more powerful test is obtained when relatively small number of observations is used to estimate the alternative and the rest are reserved to calculate the test statistic. A simulation study carried out by [Dufour and Taamouti \(2010\)](#) to compare the power-curves of the split-sample POS-based tests to that of the power envelope, reveals that using approximately 10% of the sample to estimate the alternative and the rest to calculate the test statistic, yields a power which is very close to that of the power envelope.

5 POS confidence regions

In this Section, we follow [Dufour and Taamouti \(2010\)](#) and [Coudin and Dufour \(2009\)](#) to discuss the process of building confidence regions at a given significance level α , say $C_\beta(\alpha)$, for a vector (sub-vector) of the unknown parameters β using the proposed POS-based tests. We consider again the linear regression (3.31) and suppose we wish to test the null hypothesis (3.35) against the alternative hypothesis (3.36). Formally, the idea involves finding all the values of $\beta_0 \in \mathbb{R}^{(k+1)}$ such that

$$\widehat{SN}_T(\beta_0 | \beta_1) = \sum_{t=1}^T \tilde{a}_t(\beta_0 | \beta_1)s(y_t - \beta_0' \mathbf{x}_{t-1}) + \sum_{t=1}^T \tilde{b}_t(\beta_1)s(y_t - \beta_0' \mathbf{x}_{t-1})s(y_{t-1} - \beta_0' \mathbf{x}_{t-2}) < \tilde{c}_1(\beta_0, \beta_1), \quad (5.1)$$

where the critical value $\tilde{c}_1(\beta_0, \beta_1)$ satisfies the constraint

$$P \left[\widehat{SN}_T(\beta_0 | \beta_1) > \tilde{c}_1(\beta_0, \beta_1) \mid \beta = \beta_0 \right] \leq \alpha. \quad (5.2)$$

Thus, the confidence region $C_\beta(\alpha)$ of the vector of parameters β is defined as

$$C_\beta(\alpha) = \left\{ \beta_0 : \widehat{SN}_T(\beta_0 | \beta_1) < \tilde{c}_1(\beta_0, \beta_1) \mid P[\widehat{SN}_T(\beta_0 | \beta_1) > \tilde{c}_1(\beta_0, \beta_1) \mid \beta = \beta_0] \leq \alpha \right\}. \quad (5.3)$$

Once the confidence region $C_\beta(\alpha)$ is determined, confidence intervals for the components of vector

β can be obtained using the projection techniques. Confidence sets in the form of transformations T of $\beta \in \mathbb{R}^m$, $T(C_\beta(\alpha))$ for $m \leq (k+1)$ can easily be found using said techniques. Since, for any set $C_\beta(\alpha)$

$$\beta \in C_\beta(\alpha) \implies T(\beta) \in T(C_\beta(\alpha)), \quad (5.4)$$

we have

$$P[\beta \in C_\beta(\alpha)] \geq 1 - \alpha \implies P[T(\beta) \in T(C_\beta(\alpha))] \geq 1 - \alpha, \quad (5.5)$$

where

$$T(C_\beta(\alpha)) = \{\delta \in \mathbb{R}^m : \exists \beta \in C_\beta(\alpha), T(\beta) = \delta\}. \quad (5.6)$$

From (5.4) and (5.5), it is evident that the set $T(C_\beta(\alpha))$ is a conservative confidence set for $T(\beta)$ with level $1 - \alpha$. If $T(\beta)$ is a scalar, then we have

$$P[\inf\{T(\beta_0), \text{ for } \beta_0 \in C_\beta(\alpha)\} \leq T(\beta) \leq \sup\{T(\beta_0), \text{ for } \beta_0 \in C_\beta(\alpha)\}] > 1 - \alpha. \quad (5.7)$$

To obtain valid conservative confidence intervals for the individual component β_j in regression equation (3.31) and under assumption (3.33), we follow Coudin and Dufour (2009) by implementing a global numerical optimization search algorithm to solve the problem

$$\min_{\beta \in \mathbb{R}^{(k+1)}} \beta_j \quad \text{s.c.} \quad \widehat{SN}_T(\beta_0 | \beta_1) < \tilde{c}_1(\beta_0, \beta_1), \quad \max_{\beta \in \mathbb{R}^{(k+1)}} \beta_j \quad \text{s.c.} \quad \widehat{SN}_T(\beta_0 | \beta_1) < \tilde{c}_1(\beta_0, \beta_1), \quad (5.8)$$

where the critical value $c(\beta_0, \beta_1)$ at level α , is computed using B replications of the statistic $\widehat{SN}_T^{(i)}(\beta_0 | \beta_1)$ under the null hypothesis and in turn finding its $(1 - \alpha)$ quantile. Using projection techniques, multiple tests maintain control of the overall level when performed on an arbitrary number of hypotheses.

5.1 Numerical illustration

Following Coudin and Dufour (2009), we illustrate the projection technique by generating a process with sample size $T = 500$, such that

$$y_t = \beta_0 + \beta_1 x_{1,t-1} + \beta_2 x_{2,t-1} + \varepsilon_t, \quad t = 1, \dots, T, \quad \varepsilon_t \stackrel{i.i.d.}{\sim} \begin{cases} N(0, 1) & \text{with probability 0.95} \\ N(0, 100^2) & \text{with probability 0.05} \end{cases}, \quad (5.9)$$

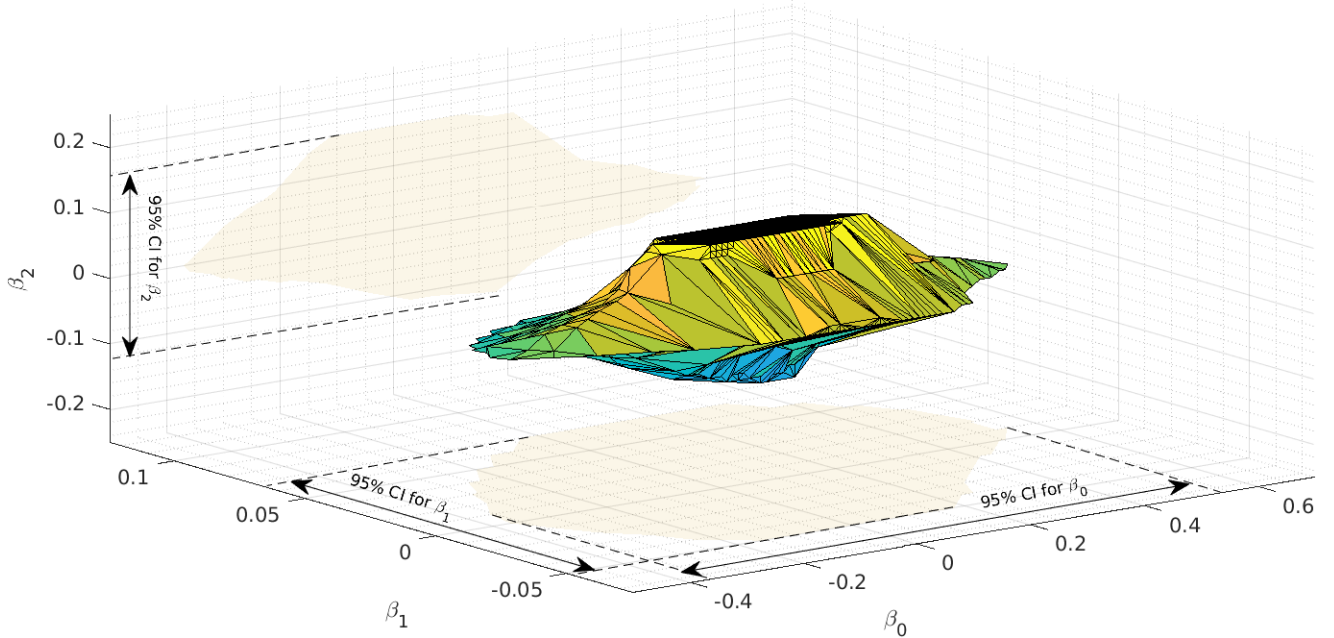
where $\beta_0 = \beta_1 = \beta_2 = 0$ and

$$\begin{bmatrix} x_{1,t} \\ x_{2,t} \end{bmatrix} = \begin{bmatrix} \theta_1 & 0 \\ 0 & \theta_2 \end{bmatrix} \begin{bmatrix} x_{1,t-1} \\ x_{2,t-1} \end{bmatrix} + \begin{bmatrix} u_{1,t} \\ u_{2,t} \end{bmatrix} \quad (5.10)$$

with $\theta_1 = \theta_2 = 0.9$. The initial vector variable $(x_{1,t}, x_{2,t})'$ is given by: $\left(\frac{u_{1,0}}{\sqrt{1-\theta_1^2}}, \frac{u_{2,0}}{\sqrt{1-\theta_2^2}} \right)'$ and $(u_{1,t}, u_{2,t})'$ is generated according to $N(\mathbf{0}, I)$, where $\mathbf{0}$ is a 2×1 zero vector and I is the identity matrix.

The exact inference procedure is conducted with $B = 999$ replications of the test statistic under the null hypothesis. As β is a vector in three-dimensional space, the confidence region and the projections can be illustrated graphically. The tests of $H_0(\beta^*) : \beta = \beta^*$ are performed on a 3D grid for $\beta^* = (\beta_0^*, \beta_1^*, \beta_2^*)$. Due to the curse of dimensionality encountered in the process of creating a grid for the parameters, the *simulated annealing optimization algorithm* is initially used to solve problem (5.8) for each parameter β_i , to obtain a practical dimension of the grid size [see Goffe et al. (1994) for a review of the simulated annealing algorithm].

Figure 1: 95% confidence region for the unknown vector $\beta = (\beta_0, \beta_1, \beta_2)$ obtained by searching a three-dimensional grid β^* using the 10% SS-POS test.



Note: The shaded regions on the $\beta_0 - \beta_1$ and $\beta_2 - \beta_1$ planes are the shadows casted by the three-dimensional confidence region, which simplify the visual identification of the 95% confidence intervals for each parameter β_i .

The optimizations were performed using MATLAB software on a high-performance computing (HPC)

cluster, by utilizing six nodes each equipped with Intel(R) Xeon(R) 16-core processors (2.40GHz). The simulated annealing algorithm’s speed of adjustment was set to 0.25, with a temperature reduction factor of 75%, an initial temperature of 50 and a convergence criteria of 0.01. All algorithms converged in less than an hour. Once the global maxima and minima for each parameter β_i were obtained, the grid was constructed by the Cartesian product of the linearly spaced distance between the β_i ’s maxima and minima.

Table 1: Comparison of the 95% confidence intervals obtained for the unknown parameters β_0 , β_1 and β_2 using the 10% SS-POS-test, with those achieved using the t -test and t -test based on [White \(1980\)](#) variance correction.

		OLS	White	10% SS-POS
β_0	95% CI	[-0.01, -0.00]	[-0.01, 0.00]	[-0.37, 0.55]
β_1	95% CI	[-1.04, -0.60]	[-1.09, -0.56]	[-0.05, 0.07]
β_2	95% CI	[0.47, 0.67]	[0.45, 0.69]	[-0.12, 0.16]

Note: The confidence intervals in bold do not contain the value of zero and imply significance at the 5% level.

It is evident that the 10% split-sample POS-based test outperforms the t -test and the t -test based on [White \(1980\)](#) variance correction test, as the former correctly fails to reject the null hypothesis of orthogonality at the 5% level, whereas the latter two tests reject the null hypothesis in favor of the alternative for almost all parameters.

6 Monte Carlo study

In this Section, we provide simulation results that illustrate the performance of the 10% SS-POS-based tests proposed earlier. We have limited our results to two groups of data generating processes (DGPs) which correspond to different symmetric and asymmetric distributions and different forms of heteroskedasticity and serial non-linear dependence.

6.1 Simulation setup

We assess the performance of the proposed 10% SS-POS-based tests in terms of size control and power, by considering various DGPs with symmetric and asymmetric distributions and different forms of heteroskedasticity. The DGPs under consideration are supposed to mimic different scenarios that are

often encountered in practical settings within the context of predictive regressions. The performance of the 10% SS-POS test is compared to that of a few other tests, by considering the following linear predictive regression model

$$y_t = \beta x_{t-1} + \varepsilon_t, \quad t = 1, \dots, T, \quad (6.1)$$

where β is an unknown parameter. Furthermore, we follow [Mankiw and Shapiro \(1986\)](#) by assuming that x_t is a stationary AR(1) process

$$x_t = \theta x_{t-1} + u_t, \quad t = 1, \dots, T, \quad (6.2)$$

such that u_t are mutually independent, and each u_t is independent of x_{t-k} for $k \geq 1$. Moreover, the disturbances (ε_t, u_t) are distributed as bivariate normal, with the contemporaneous covariance matrix

$$\Sigma_{\varepsilon u} = \begin{bmatrix} 1 & \sigma_{\varepsilon u} \\ \sigma_{\varepsilon u} & \sigma_u^2 \end{bmatrix}.$$

Therefore, there is feedback from u_t to x_t through ε_t , which implies that $\text{corr}(\varepsilon_t, x_{t+k}) \neq 0$ for $k \geq 0$. Thus, as the disturbance vector $[\varepsilon_1, \dots, \varepsilon_T]'$ is not independent of the regressor vector $[x_0, \dots, x_{T-1}]'$, the OLS estimator is biased in finite-samples and the t -statistic has a non-standard distribution. [Mankiw and Shapiro \(1986\)](#) perform an extensive simulations exercise by considering different values of the correlation between u_t and ε_t (say ρ) and find that in small samples, as θ and ρ approach unity, the t -test using asymptotic critical values leads to over rejection of the null hypothesis of unpredictability; however, the size distortions improve as $T \rightarrow \infty$.

To compare the performance of certain parametric and nonparametric tests to that of the 10% SS-POS-based test, the data is generated from model (6.1), with the stationary process x_t specified as (6.2), and by further setting

$$u_t = \rho \varepsilon_t + w_t \sqrt{1 - \rho^2} \quad (6.3)$$

for $\rho = 0, 0.1, 0.5, 0.9$, where ε_t and w_t are assumed to be independent. The initial value of x is given by: $x_0 = \frac{w_0}{\sqrt{1-\theta^2}}$. Further, w_t are generated from $N(0, 1)$ and we assign $\theta = 0.999$.

The errors ε_t are i.i.d and are categorized by two groups in our simulation study. In the first group, we consider DGPs where the error terms ε_t possess symmetric and asymmetric distributions:

1. normal distribution: $\varepsilon_t \sim N(0, 1)$;
2. Cauchy distribution: $\varepsilon_t \sim \text{Cauchy}$;
3. Student t distribution with two degrees of freedom: $\varepsilon_t \sim t(2)$;

4. Mixture of normal and Cauchy distributions: $\varepsilon_t \sim s_t|\varepsilon_t^C| - (1 - s_t)|\varepsilon_t^N|$, where ε_t^C follows Cauchy distribution, ε_t^N follows $N(0, 1)$ distribution, and

$$P(s_t = 1) = P(s_t = 0) = \frac{1}{2}. \quad (6.4)$$

The second group of DGPs represents different forms of heteroskedasticity:

5. break in variance:

$$\varepsilon_t \sim \begin{cases} N(0, 1) & \text{for } t \neq 25 \\ \sqrt{1000}N(0, 1) & \text{for } t = 25 \end{cases}; \quad (6.5)$$

6. exponential variance: $\varepsilon_t \sim N(0, \sigma_\varepsilon^2(t))$ and $\sigma_\varepsilon(t) = \exp(0.5t)$;

7. GARCH(1, 1) plus jump variance:

$$\sigma_\varepsilon^2(t) = 0.00037 + 0.0888\varepsilon_{t-1}^2 + 0.9024\sigma_\varepsilon^2(t-1), \quad (6.6)$$

$$\varepsilon_t \sim \begin{cases} N(0, \sigma_\varepsilon^2(t)) & \text{for } t \neq 25 \\ 50N(0, \sigma_\varepsilon^2(t)) & \text{for } t = 25 \end{cases}; \quad (6.7)$$

8. nonstationary GARCH(1, 1) variance: $\varepsilon_t \sim N(0, \sigma_\varepsilon^2(t))$ and

$$\sigma_\varepsilon^2(t) = 0.75\varepsilon_{t-1}^2 + 0.75\sigma_\varepsilon^2(t-1). \quad (6.8)$$

We implement the 10% SS-POS-based test and other tests which are intended to be robust against heteroskedasticity and non-normality, to test the null hypothesis of unpredictability - i.e. $H_0 : \beta = 0$. As in [Dufour and Taamouti \(2010\)](#), Monte Carlo simulations are used to compare the size and power of the 10% SS-POS test hereafter to that of the t -test, t -test based on [White \(1980\)](#) variance correction (hereafter WT-test), and sign-based test proposed by [Campbell and Dufour \(1995\)](#) (CD (1995) test hereafter). The simulation study involves $M_1 = 10,000$ iterations for evaluating the probability distribution of POS test statistic and $M_2 = 5,000$ iterations to estimate the power functions of POS test and other tests. We consider a sample size of $T = 50$ for conducting the simulation exercise. Note that the sign-based test statistic of [Campbell and Dufour \(1995\)](#) possesses a discrete distribution, as a result of which it is not possible (without randomization) to attain test whose size is exactly 5%. In our simulations study, the size of the aforementioned test is 5.95% for $T = 50$.

As in [Mankiw and Shapiro \(1986\)](#), it is further possible to consider values of ρ and θ closer to unity at which the size distortions of T-type tests are magnified. For instance, the size of the t -test in their study

is shown to be severely distorted with values of $\theta = 0.999$ and $\rho = 1.0$, given a sample size of $T = 50$. The simulations for the latter scenario can be found in the Appendix for standard normal disturbances. It must be noted that as the exact finite-sample distribution of the POS-based tests are simulated, our tests control size regardless of the values of ρ and θ - the results in figure 8 confirm these findings. It is further evident that although the size distortions for the t -test and t -test based on White (1980) variance correction improve in large samples, these tests still reject the null hypothesis at twice and thrice their nominal level respectively given a sample of $n = 500$ observations.

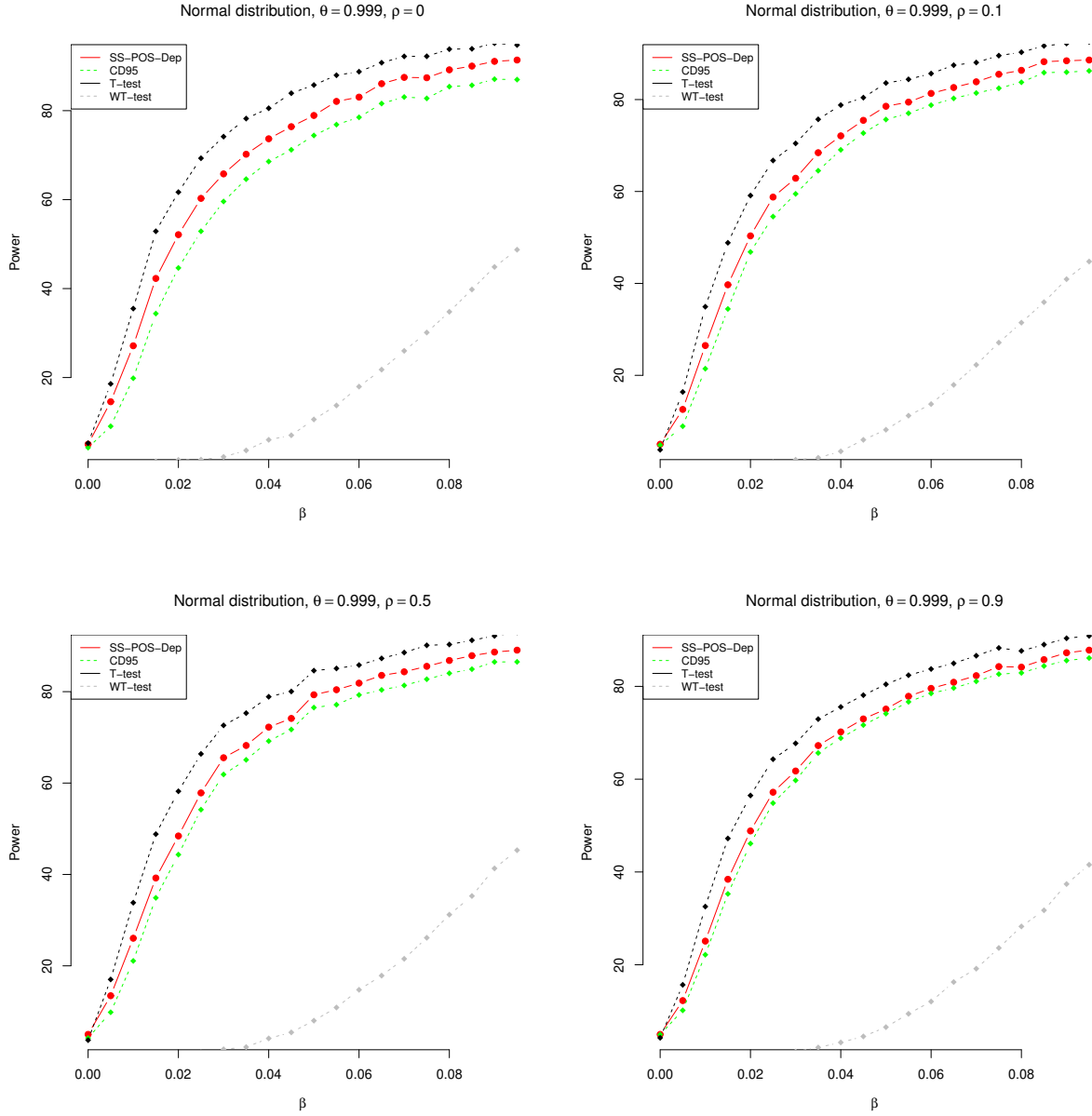
The DGPs considered in this paper have been inspired by the simulation exercises conducted in previous studies [see Mankiw and Shapiro (1986), Campbell and Dufour (1995), Coudin and Dufour (2009) and Dufour and Taamouti (2010)]. The first three DGPs all possess symmetrical distributions that are independent and identical across different observations $t = 1, \dots, T$. The Cauchy and the Student's t distribution possess heavier tails in comparison to that of the normal distribution. The standard error of the coefficients are inflated in the presence of heavy tails, as a result of which the power of the t -type tests tend to be poor in comparison to other measures of central tendency (such as the median). Furthermore, the length of the confidence intervals are extended when the data is sampled from heavy tailed distributions. DGP 4 is a mixture of Cauchy and Gaussian distribution; as such, while the errors are independent, they are not identically distributed across different observations. DGP 4 is inspired by Magdalinos and Phillips (2009), who note that when x_t is moderately explosive (with $\theta > 1$), the least squares estimator is mixed normal with Cauchy-type tail behavior and an explosive convergence rate. The second group of DGPs covers different forms of heteroskedasticity, such as conditional heteroskedasticity (e.g. stationary and non-stationary GARCH models) and other forms of nonlinear dependencies. Dufour and Taamouti (2010) show that under certain forms of heteroskedasticity, t -type tests are not valid; hence, these DGPs fit well within the domains of our study.

6.2 Simulation results

Monte Carlo simulation results are presented in Figures 2-6. These results correspond to different DGPs described in Section 6.1. The figures compare the power of the 10% SS-POS test to the t -test, WT-test, and CD (1995) test. The results are detailed below.

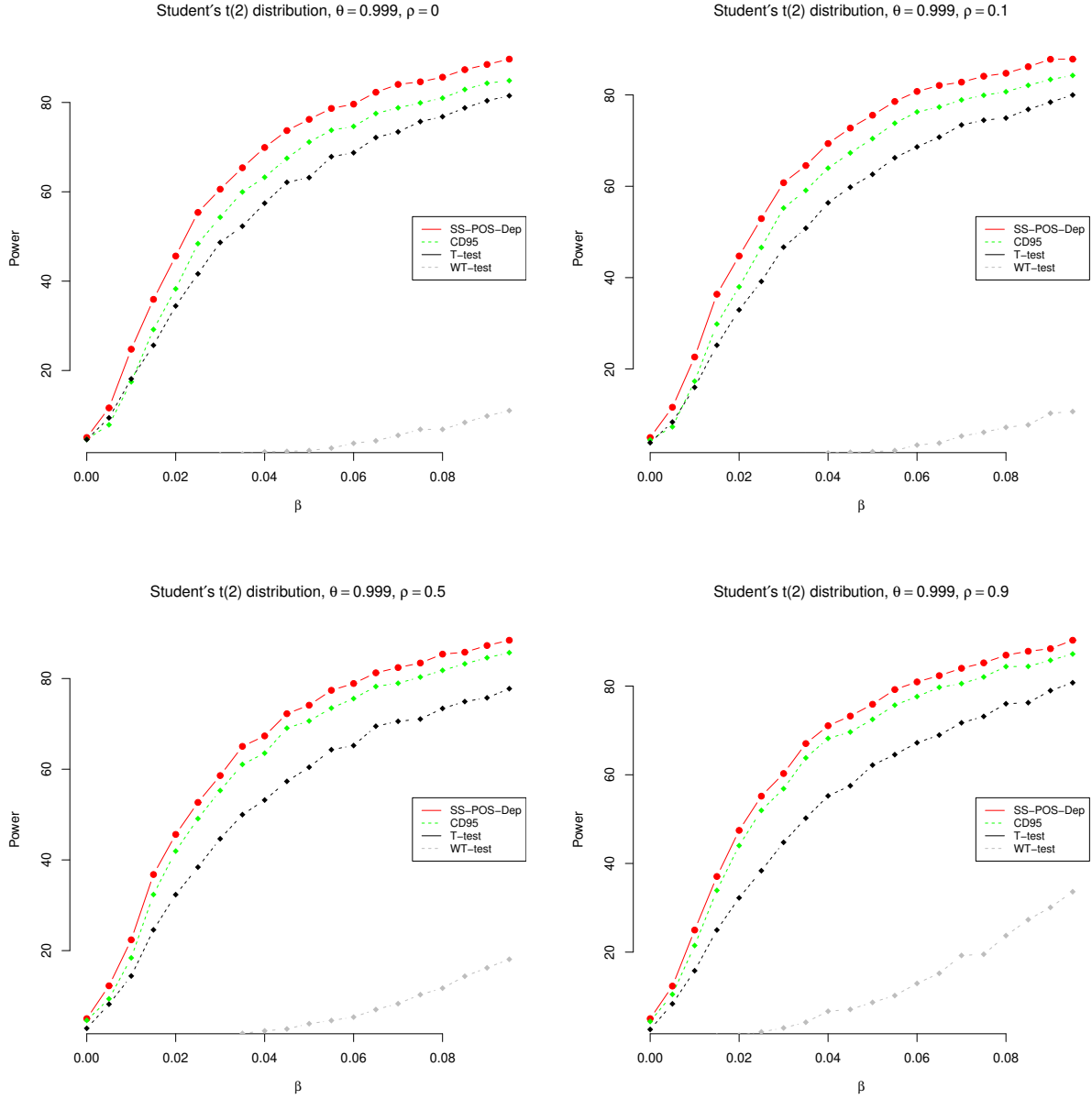
First, Figure 2 compares the power function of the above tests in the case where the error term ε_t in model (6.1) is normally distributed. Evidently, all tests control size, except for the WT-test which is undersized. We also find that t -test is more powerful than 10% SS-POS test, CD (1995) test, and the WT-test. This result is expected since under normality t -test is the most powerful test. However, the power of the 10% SS-POS test has the second greatest power among the other tests. These results hold

Figure 2: Power comparisons: different tests. Normal error distributions with different values of ρ in (6.3) and $\theta = 0.9$ in (6.2).



Note: These figures compare the power function of the 10% SS-POS test with: (1) the t -test; (2) the sign-based test proposed by Campbell and Dufour (1995) [CD (1995) test]; and (3) the t -test based on White's (1980) variance correction [WT-test].

Figure 3: Power comparisons: different tests. Student's $t(2)$ distributions with different values of ρ in (6.3) and $\theta = 0.9$ in (6.2).



Note: These figures compare the power function of the 10% SS-POS test with: (1) the t -test; (2) the sign-based test proposed by Campbell and Dufour (1995) [CD (1995) test]; and (3) the t -test based on White's (1980) variance correction [WT-test].

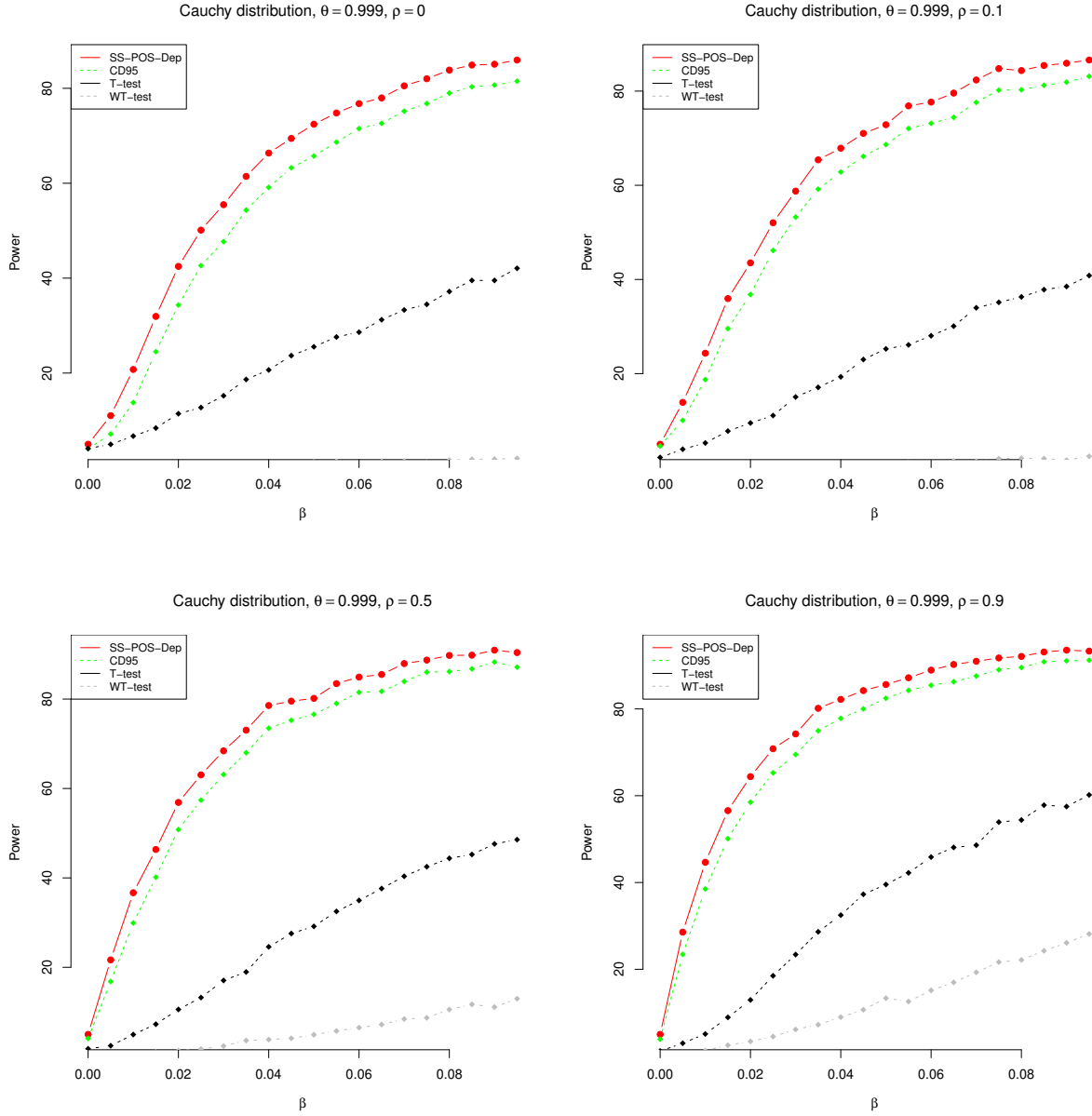
when the correlation coefficient ρ is increased, except that when there is high correlation between the error terms ε_t and w_t the power curves of t -test, 10% SS-POS test and CD (1995) test get closer to one another.

Second, Figure 4 corresponds to the scenario where the error term ε_t follows a Cauchy distribution. We can observe that the 10% SS-POS test is more powerful than the CD (1995) test, WT-test, and the t -test. It appears that the latter two tests are undersized. The 10% SS-POS test and CD (1995) test have significantly greater power than the WT-test and the t -test for small values (0 and 0.1) of the correlation coefficient ρ , but the difference in power decreases when we increase ρ .

Third, Figure 5 corresponds to the case where the error term ε_t follows a mixture of normal and Cauchy distributions. The results suggest that the t -test is invalid, as it over rejects under the null hypothesis of unpredictability for all values of ρ . Moreover, the 10% SS-POS test is again more powerful than the CD (1995), t -test, and the WT-test. The difference in power is much more significant when the correlation coefficient ρ is smaller.

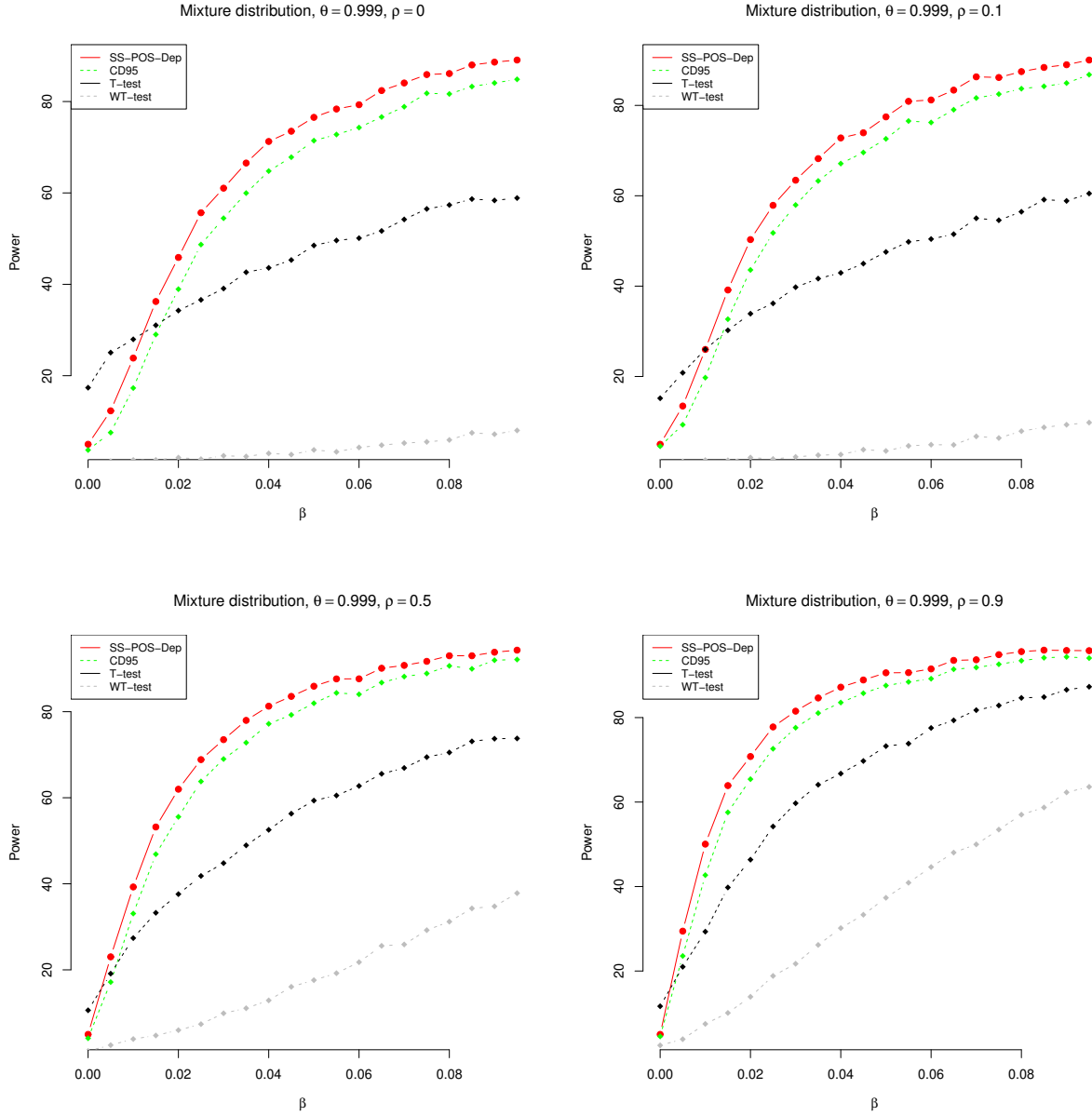
Finally, Figures 6 compare the power function of the 10% SS-POS test, CD (1995) test, WT-test, and t -test in the case where ε_t follows normal distribution with a break in variance. Figure 6 shows that in the presence of break in variance, the WT-test and the t -test are undersized, whereas 10% SS-POS test and CD (1995) test control size. In addition, 10% SS-POS test has more power than the other tests. The CD (1995) test has the second best power, whereas the t -test and WT-test are plagued with poor power. The power of these tests improve when the correlation coefficient is increased ρ .

Figure 4: Power comparisons: different tests. Cauchy error distributions with different values of ρ in (6.3) and $\theta = 0.9$ in (6.2).



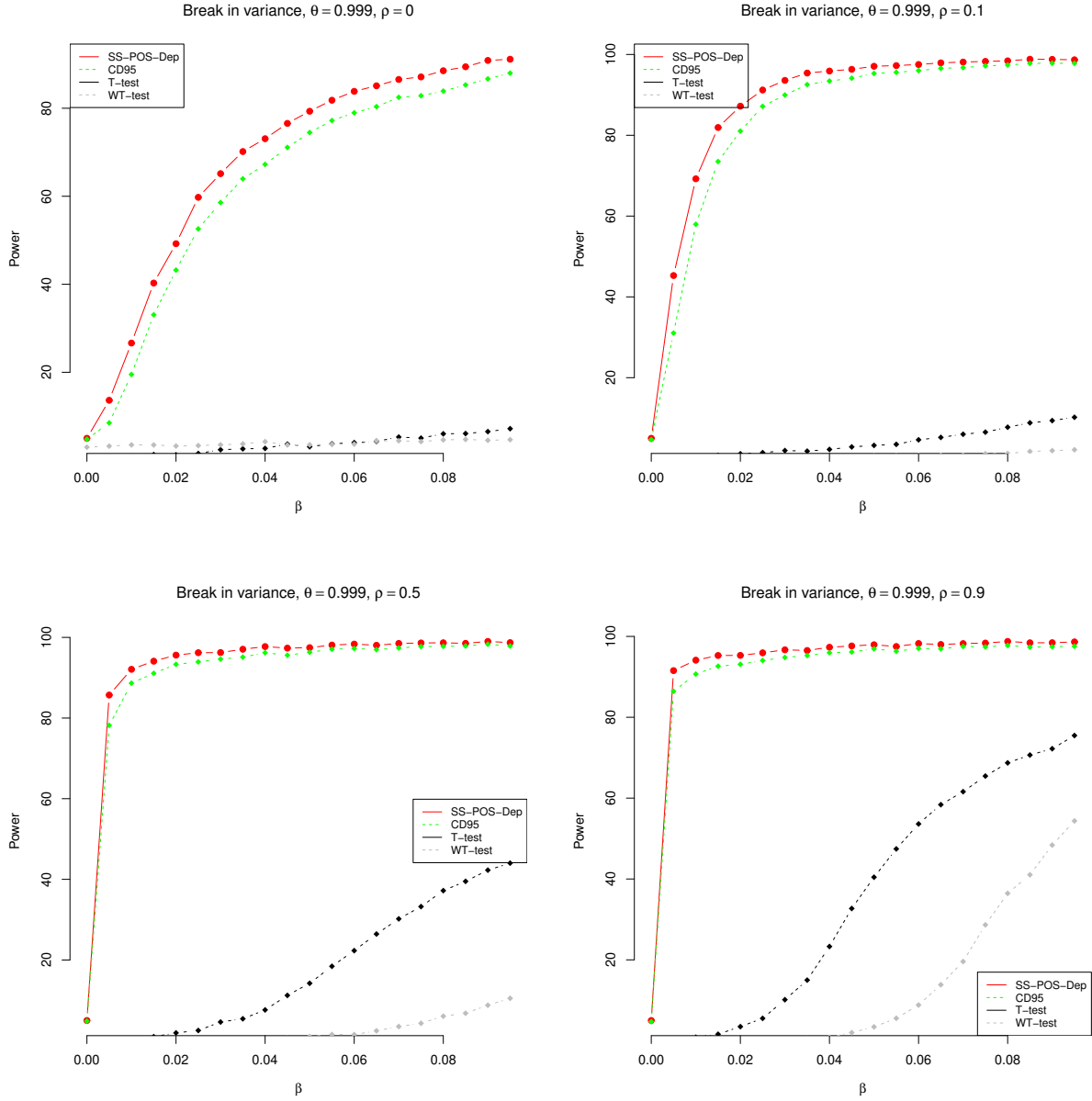
Note: These figures compare the power function of the 10% SS-POS test with: (1) the t -test; (2) the sign-based test proposed by Campbell and Dufour (1995) [CD (1995) test]; and (3) the t -test based on White's (1980) variance correction [WT-test].

Figure 5: Power comparisons: different tests. Mixture error distributions with different values of ρ in (6.3) and $\theta = 0.9$ in (6.2).



Note: These figures compare the power function of the 10% SS-POS test with: (1) the t -test; (2) the sign-based test proposed by Campbell and Dufour (1995) [CD (1995) test]; and (3) the t -test based on White's (1980) variance correction [WT-test].

Figure 6: Power comparisons: different tests. Normal error distributions with break in variance, different values of ρ in (6.3) and $\theta = 0.9$ in (6.2).



Note: These figures compare the power function of the 10% SS-POS test with: (1) the t -test; (2) the sign-based test proposed by Campbell and Dufour (1995) [CD (1995) test]; and (3) the t -test based on White's (1980) variance correction [WT-test].

7 Empirical application

In this Section, we consider an empirical application of the proposed 10% SS-POS tests to illustrate its practical relevance. Valuation ratios are widely considered as predictors of stock returns and are generally known to be persistent. Therefore, they fit well within the framework of our study. In what follows, we specifically divert our attention to an application in the context of stock return predictability using the said ratios.

7.1 Stock return predictability using valuation ratios

Many studies have investigated the predictive power of valuation ratios on excess stock returns. Dividend-price and earnings-price ratios are among few that were the focus of study in the early 1980s. The attention to these ratios was heightened when [Rozeff \(1984\)](#), [Fama and French \(1988a\)](#), and [Campbell and Shiller \(1988\)](#) showed the ratios positive correlation with ex-post stock returns. [Fama and French \(1988a\)](#) find that in short horizons dividend yields only explain a small fraction of the variation in time-varying returns, yet in longer horizons (beyond one year) this proportion is significantly increased. [Campbell and Shiller \(1988\)](#) employ a two-variable system approach with the lagged log of the dividend-price ratio together with the lagged real dividend growth rate, to show significant predictive power on stock returns.

These studies are typically performed by regressing the excess returns on a constant and a lagged variable. The conventional t -test is then used to make inference concerning predictability. However, most of these studies are based on the presumption of the stationarity of the predictors, where the t -statistic is approximately normally distributed in large samples. Unfortunately, this is not the case in the presence of highly persistent variables. Even when the predictors are stationary, asymptotic critical values are not a good approximation for those obtained in finite-sample distributions. In the presence of highly persistent predictors, the innovations are greatly correlated with the returns, and thus, the t -statistic has a non-standard distribution which leads to the over-rejection of the null hypothesis of orthogonality [see. [Elliott and Stock \(1994\)](#), [Mankiw and Shapiro \(1986\)](#), [Stambaugh \(1999\)](#) and [Campbell and Yogo \(2006\)](#)].

Most studies address the issue of persistency by making inference based on more accurate approximations of the finite-sample distribution of the test-statistic. This is accomplished either by relying on exact finite-sample theory under the assumption of normality [see. [Evans and Savin \(1981, 1984\)](#) and [Stambaugh \(1999\)](#)] or local-to-unity asymptotics [see [Elliott and Stock \(1994\)](#), [Campbell and Yogo \(2006\)](#) and [Torous et al. \(2004\)](#)]. More recently [Taamouti et al. \(2014\)](#) confirm the predictability power of the valuation ratios using monthly data, in a nonparametric and model-free copula-based Granger causality

framework.

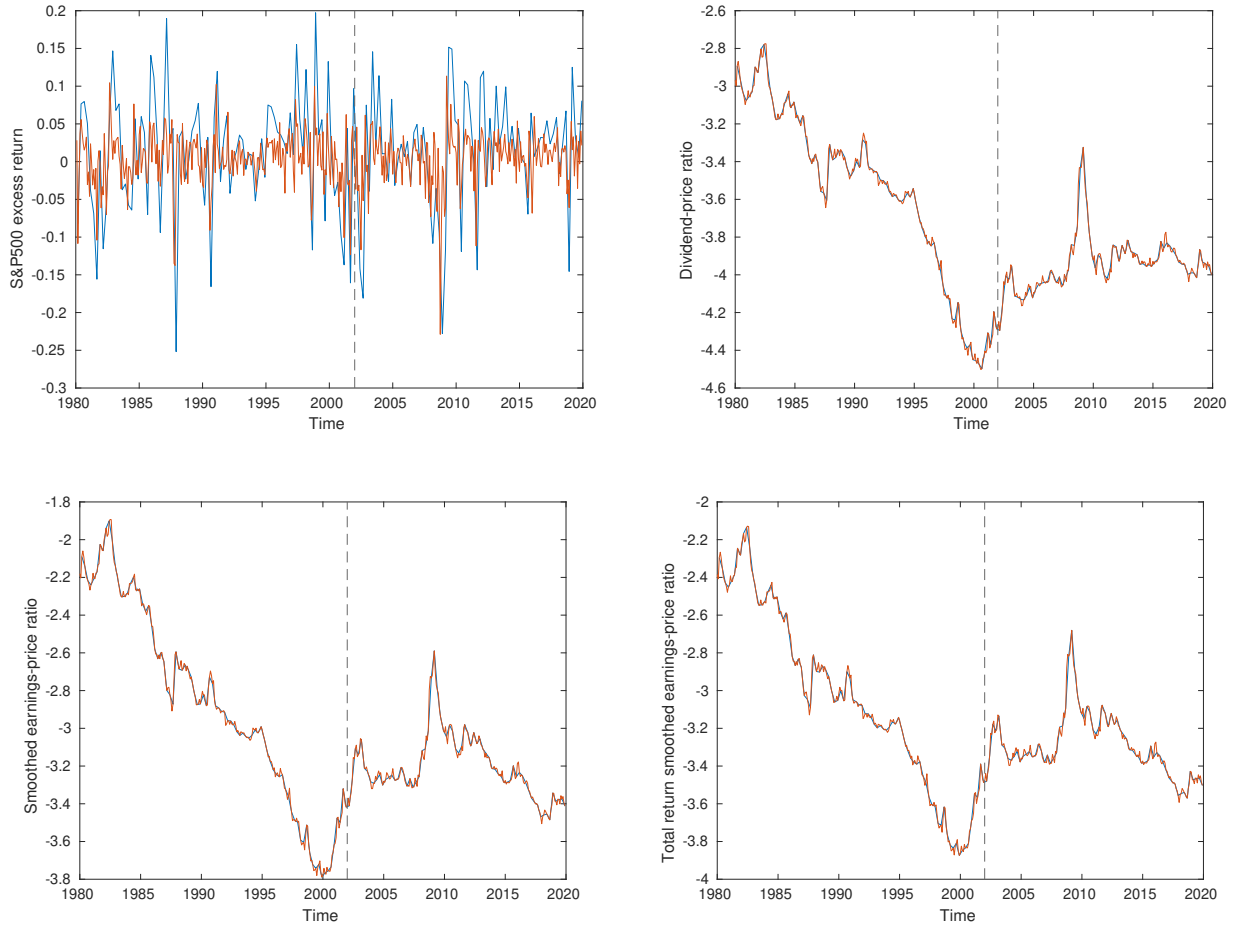
In this Section, we use our exact 10% SS-POS-based test to make inference and compare the predictive power of the valuation ratios (dividend-price ratio, smoothed earnings-price ratio, and total return smoothed earnings-price ratio) on stock market returns. The smoothed earnings-price ratio is proposed by [Campbell and Shiller \(1988, 2001\)](#) upon observing numerous spikes in the plot of the earnings-price ratio that had not been observed in the dividend-price ratio. The spikes were explained to be caused by recessions, which temporarily suppress corporate earnings. The latter measure is the ratio of the ten-year moving average of real earnings to current real prices and is said to possess better forecasting powers. Furthermore, the total return smoothed earnings-price ratio is recently incorporated in forecasting, as a consequence of the changes in corporate payout policy documented by [Bunn et al. \(2014\)](#) and [Jivraj and Shiller \(2017\)](#). Share repurchases (as opposed to dividends) have become the dominant approach for distributing cash to shareholders in the U.S. which may impact the smoothed earnings-price ratio through changes in growth of earnings per share. The total return smoothed earnings-price ratio corrects for this bias by reinvesting the dividends into the price index, such that the earnings per share is appropriately scaled.

7.1.1 Data description

Our data consists of monthly and quarterly observations of the aggregate S&P500 composite index for the period spanning from March 1980 to December 2019 for a total of 480 trading months or 160 trading quarters. We consider the logarithmic returns on the S&P500 in excess of the 30-day and 90-day T-bill rate. The valuation ratios under consideration are: dividend-price ratio, smoothed earnings-price ratio, and total return smoothed earnings-price ratio. The nominal monthly and quarterly prices of the value-weighted S&P500 composite index, as well as the corresponding dividends and earnings are obtained from a database provided on Robert Shiller’s website. The 30-day and 90-day Treasury bill returns, on the other hand, have been retrieved from the Center for Research in Security Prices (CRSP).

At first glance figure 7 suggests that the predictors under consideration are highly persistent and potentially non-stationary. This visual assessment is confirmed in table 2, which presents the test statistics for the augmented Dickey-Fuller test (ADF hereafter) for all the time series. Evidently, for the full sample and the two sub-periods we fail to reject the null hypothesis of nonstationarity. The testing procedure entails estimating and testing the model in its most general form using more deterministic components than the hypothesized DGP (i.e. including both an intercept and a trend), and following [Phillips and Perron \(1988\)](#) sequential testing strategy thereafter, eliminating the unnecessary nuisance parameters in the process. At each stage, if the null hypothesis of orthogonality is rejected, we conclude

Figure 7: Monthly and quarterly S&P500 excess stock returns, dividend-price, smoothed earnings-price and total return smoothed earnings-price ratios.



Note: The data spans from March 1980 to December 2019 for a total of 480 trading months and 160 trading quarters respectively. The red and the blue lines in turn correspond to the quarterly and monthly samples. To assess the predictability power of the valuation ratios, we further consider two sub-periods separated by the dashed line: one spanning from March 1980 to January 2002 and another in the period of January 2002 to January 2019.

that the model is correctly specified and that the process is stationary. Otherwise, the test is performed on a more restricted model. This procedure is continued until we arrive at the most basic form of the model (with no intercept or a trend), or until the null hypothesis of unit root is rejected. As it is evident, all valuation ratios reject the null hypothesis of non-stationarity at the 5% level.

7.1.2 Predictability results

The projection technique based on the proposed 10% SS-POS test is used to build simultaneous confidence sets for the parameters of the regressions of the excess returns against the dividend-price ratio, smoothed earnings-price ratio of [Campbell and Shiller \(1988\)](#) and the total return smoothed earnings-price ratio of [Bunn et al. \(2014\)](#) and [Jivraj and Shiller \(2017\)](#) respectively. The results for different sub-periods and the full sample are reported in table 3. As explained in Section 5, each simultaneous confidence set is obtained by collecting all pairs of (β_0, β_1) that are not rejected using our 10% SS-POS test. Thus, a grid search is applied over an appropriate range² and 95% level confidence sets are constructed by retaining all the pairs (β_0, β_1) that are not rejected by the 10% SS-POS test. Alternatively, the simulated annealing algorithm can be used to solve the optimization problem (5.8) for each parameter β_i .

The 95% confidence intervals for the parameters β_0 and β_1 contain zero for the regressions of the excess returns against all the predictors using the t -test based on [White \(1980\)](#) for all periods in our study. However, using the 10% SS-POS based test, there is evidence of predictability in quarterly data in favor of all predictors for the period spanning from January 2002 to January 2019. Our findings are in line with those of [Campbell and Yogo \(2006\)](#) who do not find any evidence of predictability in favor of any of the predictors in the period spanning from 1952-2002.

²See Section 5.1.

Table 2: Results of the ADF test on the real and nominal time-series using the general-to-specific sequential testing procedure

Series	Obs.	Predictor	p	$\delta + \mu$	μ	None
<i>Panel A: 1980-2002</i>						
Monthly	264	$r_t^m - r_t^f$	1	-10.959***	--	--
		d/p_t	2	-2.217	-0.657	2.026
		e/p_t'	2	-2.248	-1.171	1.721
		e/p_t''	2	-2.160	-1.376	1.544
Quarterly	88	$r_t^m - r_t^f$	0	-9.026***	--	--
		d/p_t	0	-2.209	-0.777	1.830
		e/p_t'	0	-1.816	-1.210	1.576
		e/p_t''	0	-1.669	-1.400	1.391
<i>Panel B: 2002-2019</i>						
Monthly	215	$r_t^m - r_t^f$	0	-11.369***	--	--
		d/p_t	1	-2.853	-2.983**	--
		e/p_t'	1	-2.317	-1.938	-0.027
		e/p_t''	1	-2.389	-1.935	0.009
Quarterly	72	$r_t^m - r_t^f$	0	-7.513***	--	--
		d/p_t	1	-3.261*	-3.278**	--
		e/p_t'	0	-2.374	-1.915	-0.095
		e/p_t''	0	-2.448	-1.901	-0.057
<i>Panel C: 1980-2019</i>						
Monthly	479	$r_t^m - r_t^f$	1	-14.347***	--	--
		d/p_t	2	-1.861	-2.104	0.935
		e/p_t'	2	-1.802	-2.042	1.136
		e/p_t''	2	-1.965	-2.161	1.056
Quarterly	160	$r_t^m - r_t^f$	0	-11.848***	--	--
		d/p_t	0	-1.762	-2.051	0.876
		e/p_t'	0	-1.732	-1.995	1.084
		e/p_t''	0	-1.897	-2.114	0.998

Note: This table reports the results of the ADF test on the time-series in the predictive regression model. The approach involves using the general-to-specific sequential testing procedure to test the null hypothesis of non-stationarity, where the general form of the model is:

$$\Delta x_t = \rho x_{t-1} + \sum_{i=1}^{p-1} \psi_i \Delta x_{t-i} + \mu + \delta t + u_t, \quad u_t \sim IID(0, \sigma^2). \quad (7.1).$$

The corresponding test statistics are reported in turn for the general form of the model (including the trend δ and intercept c), the more restrictive form constituting only of an intercept c , and the case where neither the trend nor the intercept are present. The variables are defined as follows: $r_t^m - r_t^f$ are the excess logarithmic stock returns, d/p_t is the dividend-price ratio, e/p_t' is the smoothed earnings-price ratio and e/p_t'' is the total return smoothed earnings-price ratio respectively. The statistics with three asterisks (***), two asterisks (**) and one asterisk (*) are significant at the 1%, 5% and the 10% levels respectively.

Table 3: Predictability results for the dividend-price, earnings-price and the smoothed earnings-price ratios

Series	Predictor	$\hat{\beta}$	95% confidence interval	
			10% SS-POST	WT-test
<i>Panel A: 1980-2002</i>				
Monthly	d/p_t	0.002	$[-0.024, 0.036]$	$[-0.008, 0.011]$
	e/p_t'	-0.001	$[-0.044, 0.046]$	$[-0.009, 0.008]$
	e/p_t''	-0.001	$[-0.052, 0.049]$	$[-0.010, 0.010]$
Quarterly	d/p_t	0.009	$[-0.104, 0.106]$	$[-0.028, 0.047]$
	e/p_t'	0.003	$[-0.116, 0.104]$	$[-0.029, 0.036]$
	e/p_t''	0.004	$[-0.126, 0.104]$	$[-0.033, 0.040]$
<i>Panel B: 2002-2019</i>				
Monthly	d/p_t	0.019	$[-0.220, 0.330]$	$[-0.015, 0.053]$
	e/p_t'	0.012	$[-0.079, 0.191]$	$[-0.018, 0.042]$
	e/p_t''	0.010	$[-0.080, 0.180]$	$[-0.021, 0.040]$
Quarterly	d/p_t	0.119	[0.159, 0.899]	$[-0.001, 0.238]$
	e/p_t'	0.089	[0.042, 0.632]	$[-0.018, 0.197]$
	e/p_t''	0.084	[0.058, 0.697]	$[-0.026, 0.194]$
<i>Panel C: 1980-2019</i>				
Monthly	d/p_t	0.002	$[-0.041, 0.069]$	$[-0.006, 0.010]$
	e/p_t'	0.0003	$[-0.021, 0.049]$	$[-0.007, 0.007]$
	e/p_t''	0.0001	$[-0.039, 0.061]$	$[-0.008, 0.008]$
Quarterly	d/p_t	0.136	$[-0.094, 0.146]$	$[-0.017, 0.044]$
	e/p_t'	0.008	$[-0.099, 0.121]$	$[-0.020, 0.036]$
	e/p_t''	0.009	$[-0.113, 0.147]$	$[-0.023, 0.041]$

Note: This table presents the coefficient estimates, as well as the 95% confidence intervals for the variables considered in our study, by inverting the proposed 10% SS-POS-based tests and the t -test based on [White \(1980\)](#) variance correction. The alternatives for the 10% SS-POS tests are obtained by running OLS regressions of the excess returns against the dividend-price, smoothed earnings-price and the total return smoothed earnings-price ratios. The regressions assume the form

$$r_t^m - r_t^f = \beta_0 + \beta_1 x_{t-1} + \varepsilon_t, \quad (7.2)$$

where r_t is the ex-post excess returns and x_{t-1} is the ex-ante predictor. The projection-based 95% confidence intervals for the 10% SS-POS tests are obtained by testing $H_0(\beta^*) : \beta = \beta^*$ on a grid for $\beta^* = (\beta_0^*, \beta_1^*)$, where the grid dimension is found by solving the optimization problem (5.8) for each parameter β_0 and β_1 using the simulated annealing algorithm, and consequently equally dividing each interval and finding their Cartesian product. The intervals in bold do not contain the value of zero and imply significance at the 5% level.

8 Conclusion

In this paper, we propose point-optimal sign-based tests for inference in linear and nonlinear predictive regressions in the presence of stochastic (or fixed) regressors. One motivation is to build valid (control the size whatever the sample size) tests for linear and nonlinear predictability of stock returns. The most popular predictors of stock returns (e.g. dividend-price ratio, earning-price ratio, etc.) are known to be persistent with errors that are correlated with the shock in the returns. This makes the classical predictability tests invalid, particularly when the sample size is small or moderate. In addition, the proposed sign-based tests are exact, distribution-free and robust against heteroskedasticity of unknown form, and further allow for serial (nonlinear) dependence. Additionally, they may be inverted to build confidence regions for the parameters of the regression function. Since the point-optimal sign-based tests depend on the alternative hypothesis, an adaptive approach based on the split-sample technique is suggested to choose the appropriate alternative that controls the size and maximizes the power.

We presented a Monte Carlo study to assess the performance of the proposed “quasi”-point-optimal sign test by comparing its size and power to those of certain existing tests that are intended to be robust against heteroskedasticity. We considered different DGPs to illustrate different contexts that one can encounter in practice. The results show that the 10% split-sample point-optimal sign test is more powerful than the t -test, [Campbell and Dufour \(1995\)](#) sign-based test, and the t -test based on [White \(1980\)](#) variance correction.

Finally, the proposed tests are used to assess the predictive power of some financial predictors, such as the dividend-price and earnings-price ratios, as well as the smoothed earnings-price ratio of [Campbell and Shiller \(1988, 2001\)](#) on the annualized monthly excess stock returns. Our study suggests predictability in favor of all the predictors for the quarterly data in the period spanning from 2002 to 2009, which is consistent with the findings of [Campbell and Yogo \(2006\)](#). We further reaffirm the findings of [Campbell and Yogo \(2006\)](#) who do not find any evidence of predictability in favor of any of the predictors in the period spanning from 1952-2002.

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9 Appendix: Proofs

Proof of Theorem 1. From Assumption (2.3), the equalities (9.1) and (9.2) are derived as follows

$$P[\varepsilon_t \geq 0 \mid X] = \mathbb{E}(P[\varepsilon_t \geq 0 \mid \boldsymbol{\varepsilon}_{t-1}, X]) = \frac{1}{2} \quad (9.1)$$

with

$$\boldsymbol{\varepsilon}_0 = \{\emptyset\}, \quad \boldsymbol{\varepsilon}_{t-1} = \{\varepsilon_1, \dots, \varepsilon_{t-1}\}, \quad \text{for } t \geq 2$$

and

$$P[\varepsilon_t \geq 0 \mid \mathbb{S}_{t-1}^\varepsilon, X] = P[\varepsilon_t \geq 0 \mid \boldsymbol{\varepsilon}_{t-1}, X] = \frac{1}{2}, \quad (9.2)$$

with

$$\mathbb{S}_0^\varepsilon = \{\emptyset\}, \quad \mathbb{S}_{t-1}^\varepsilon = \{s(\varepsilon_1) = s_1, \dots, s(\varepsilon_{t-1}) = s_{t-1}\}, \quad \text{for } t \geq 2,$$

We define the vector of signs $U(T) = (s(y_1), \dots, s(y_T))'$, where $s(y_t) = \mathbb{1}_{\mathbb{R}^+ \cup 0}\{y_t\}$. Thus, given model (2.1), under the null hypothesis of unpredictability, $(s(y_1), \dots, s(y_T))'$ is equivalent to the signs of error terms $(s(\varepsilon_1), \dots, s(\varepsilon_T))'$. Thus, under the null hypothesis, the likelihood function of the sample in terms of the signs is given by

$$\begin{aligned} L(U(T), \mathbf{0}, X) &= P[s(y_1) = s_1, \dots, s(y_T) = s_T \mid X] \\ &= P[s(\varepsilon_1) = s_1, \dots, s(\varepsilon_T) = s_T \mid X] \\ &= \prod_{t=1}^T P[\varepsilon_t \geq 0 \mid \boldsymbol{\varepsilon}_{t-1}, X]^{s(\varepsilon_t)} (1 - P[\varepsilon_t \geq 0 \mid \boldsymbol{\varepsilon}_{t-1}, X])^{1-s(\varepsilon_t)} \\ &= \prod_{t=1}^T \left(\frac{1}{2}\right)^{s(\varepsilon_t)} \left(1 - \frac{1}{2}\right)^{1-s(\varepsilon_t)} \\ &= \left(\frac{1}{2}\right)^T \end{aligned}$$

Hence, it can be concluded that conditional on X and under the null hypothesis of orthogonality $s(y_1), \dots, s(y_T) \stackrel{i.i.d}{\sim} Bi(1, 0.5)$. ■

Proof of Proposition 1. The likelihood function of sample in terms of signs $s(y_1), \dots, s(y_T)$

$$L(U(T), \boldsymbol{\beta}, X) = P[s(y_1) = s_1, \dots, s(y_T) = s_T \mid X] = \prod_{t=1}^T P(s(y_t) = s_t \mid \mathbb{S}_{t-1}, X),$$

for

$$\mathbb{S}_0 = \{\emptyset\}, \quad \mathbb{S}_{t-1} = \{s(y_1) = s_1, \dots, s(y_{t-1}) = s_{t-1}\}, \quad \text{for } t \geq 2,$$

and

$$P[s(y_1) = s_1 \mid \mathbb{S}_0, X] = P[s(y_1) = s_1 \mid X],$$

where each s_t , for $1 \leq t \leq T$, takes two possible values 0 and 1. According to model (2.1) and assumption (2.3), under the null hypothesis the signs $s(y_1), \dots, s(y_T)$ are i.i.d according to $Bi(1, 0.5)$,

$$P[s(y_t) = 1 \mid X] = P[s(y_t) = 0 \mid X] = \frac{1}{2}, \text{ for } t = 1, \dots, T,$$

Consequently, under H_0

$$L_0(U(T), \mathbf{0}, X) = \prod_{t=1}^T P[s(y_t) = s_t \mid X] = \left(\frac{1}{2}\right)^T$$

and under H_1 we have

$$L_1(U(T), \beta_1, X) = \prod_{t=1}^T P[s(y_t) = s_t \mid \mathbb{S}_{t-1}, X]$$

where now, for $t = 1, \dots, T$,

$$y_t = \beta_1' \mathbf{x}_{t-1} + \varepsilon_t$$

The log-likelihood ratio is given by

$$\ln \left\{ \frac{L_1(U(T), \beta_1, X)}{L_0(U(T), \mathbf{0}, X)} \right\} = \sum_{t=1}^T \ln \{P[s(y_t) = s_t \mid \mathbb{S}_{t-1}, X]\} - T \ln \left\{ \frac{1}{2} \right\}.$$

According to Neyman-Pearson lemma [see e.g. Lehmann (1959), page 65], the best test to test H_0 against H_1 , based on $s(y_1), \dots, s(y_T)$, rejects H_0 when

$$\ln \left\{ \frac{L_1(U(T), \beta_1, X)}{L_0(U(T), \mathbf{0}, X)} \right\} \geq c$$

or when

$$\sum_{t=1}^T \ln \{P[s(y_t) = s_t \mid \mathbb{S}_{t-1}, X]\} \geq c,$$

The critical value, say c , is given by the smallest constant c such that

$$P \left(\ln \left\{ \frac{L_1(U(T), \beta_1, X)}{L_0(U(T), \mathbf{0}, X)} \right\} > c \mid H_0 \right) \leq \alpha.$$

Notice that, for $t = 1, \dots, T$

$$P[s(y_t) = s_t \mid \mathbb{S}_{t-1}, X] = P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]^{s(y_t)} P[y_t < 0 \mid \mathbb{S}_{t-1}, X]^{(1-s(y_t))}, \text{ for } t = 1, \dots, T. \quad (9.3)$$

From (9.3), we have

$$\begin{aligned}
\ln \left\{ \prod_{t=1}^T P[s(y_t) = s_t \mid \mathbb{S}_{t-1}, X] \right\} &= \ln \left\{ \prod_{t=1}^T P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]^{s(y_t)} P[y_t < 0 \mid \mathbb{S}_{t-1}, X]^{(1-s(y_t))} \right\} \\
&= \sum_{t=1}^T s(y_t) \ln \{P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]\} \\
&\quad + \sum_{t=1}^T (1 - s(y_t)) \ln \{P[y_t < 0 \mid \mathbb{S}_{t-1}, X]\} \\
&= \sum_{t=1}^T s(y_t) \ln \{P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]\} + \sum_{t=1}^T \ln \{P[y_t < 0 \mid \mathbb{S}_{t-1}, X]\} \\
&\quad - \sum_{t=1}^T s(y_t) \ln \{P[y_t < 0 \mid \mathbb{S}_{t-1}, X]\} \\
&= \sum_{t=1}^T s(y_t) \ln \left\{ \frac{P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]}{P[y_t < 0 \mid \mathbb{S}_{t-1}, X]} \right\} + \sum_{t=1}^T \ln \{P[y_t < 0 \mid \mathbb{S}_{t-1}, X]\}
\end{aligned}$$

Thus, the best test to test H_0 against H_1 , based on $s(y_1), \dots, s(y_T)$, rejects H_0 when

$$\ln \left\{ \frac{L_1(U(T), \beta_1, X)}{L_0(U(T), \mathbf{0}, X)} \right\} = \sum_{t=1}^T s(y_t) \ln \left\{ \frac{P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]}{P[y_t < 0 \mid \mathbb{S}_{t-1}, X]} \right\} + \sum_{t=1}^T \ln \{P[y_t < 0 \mid \mathbb{S}_{t-1}, X]\} - T \ln \left\{ \frac{1}{2} \right\} \geq c$$

or when

$$\ln \left\{ \frac{L_1(U(T), \beta_1, X)}{L_0(U(T), \mathbf{0}, X)} \right\} = \sum_{t=1}^T s(y_t) \ln \left\{ \frac{P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]}{P[y_t < 0 \mid \mathbb{S}_{t-1}, X]} \right\} \geq c_1(\beta_1)$$

where the critical value $c_1(\beta_1)$ is chosen so that

$$P[S_T(\beta_1) > c_1(\beta_1) \mid H_0] \leq \alpha$$

α is an arbitrary significance level. ■

Proof of Corollary 1. From test statistic $S_T(\beta_1)$ in Proposition 1 and under assumption **A1**, we have:

$$\begin{aligned}
\tilde{S}_T(\beta_1) &= \sum_{t=1}^T s(y_t) \ln \left\{ \frac{P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]}{P[y_t < 0 \mid \mathbb{S}_{t-1}, X]} \right\} \\
&= \sum_{t=1}^T s(y_t) \{ \ln \{P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]\} - \ln \{P[y_t < 0 \mid \mathbb{S}_{t-1}, X]\} \} \\
&= \sum_{t=1}^T s(y_t) \left\{ \begin{array}{l} \ln \{P[y_t \geq 0 \mid y_{t-1} \geq 0, X]^{s(y_{t-1})} P[y_t \geq 0 \mid y_{t-1} < 0, X]^{1-s(y_{t-1})}\} \\ - \ln \{P[y_t < 0 \mid y_{t-1} \geq 0, X]^{s(y_{t-1})} P[y_t < 0 \mid y_{t-1} < 0, X]^{1-s(y_{t-1})}\} \end{array} \right\}
\end{aligned}$$

$$= \sum_{t=1}^T s(y_t) \left\{ \begin{array}{l} s(y_{t-1}) \ln \{P[y_t \geq 0 \mid y_{t-1} \geq 0, X]\} + (1 - s(y_{t-1})) \ln \{P[y_t \geq 0 \mid y_{t-1} < 0, X]\} \\ -s(y_{t-1}) \ln \{P[y_t < 0 \mid y_{t-1} \geq 0, X]\} - (1 - s(y_{t-1})) \ln \{P[y_t < 0 \mid y_{t-1} < 0, X]\} \end{array} \right\}$$

Observe that:

$$\begin{aligned} \ln \left\{ \frac{P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]}{P[y_t < 0 \mid \mathbb{S}_{t-1}, X]} \right\} &= \ln \left\{ P[y_t \geq 0 \mid y_{t-1} \geq 0, X]^{s(y_{t-1})} P[y_t \geq 0 \mid y_{t-1} < 0, X]^{1-s(y_{t-1})} \right\} \\ &\quad - \ln \left\{ P[y_t < 0 \mid y_{t-1} \geq 0, X]^{s(y_{t-1})} P[y_t < 0 \mid y_{t-1} < 0, X]^{1-s(y_{t-1})} \right\} \\ &= s(y_{t-1}) \ln \{P[y_t \geq 0 \mid y_{t-1} \geq 0, X]\} \\ &\quad + (1 - s(y_{t-1})) \ln \{P[y_t \geq 0 \mid y_{t-1} < 0, X]\} \\ &\quad - s(y_{t-1}) \ln \{P[y_t < 0 \mid y_{t-1} \geq 0, X]\} \\ &\quad - (1 - s(y_{t-1})) \ln \{P[y_t < 0 \mid y_{t-1} < 0, X]\} \\ &= s(y_{t-1}) \ln \{P[y_t \geq 0 \mid y_{t-1} \geq 0, X]\} + \ln \{P[y_t \geq 0 \mid y_{t-1} < 0, X]\} \\ &\quad - s(y_{t-1}) \ln \{P[y_t \geq 0 \mid y_{t-1} < 0, X]\} - s(y_{t-1}) \ln \{P[y_t < 0 \mid y_{t-1} \geq 0, X]\} \\ &\quad - \ln \{P[y_t < 0 \mid y_{t-1} < 0, X]\} + s(y_{t-1}) \ln \{P[y_t < 0 \mid y_{t-1} < 0, X]\} \\ &= s(y_{t-1}) \left\{ \ln \left\{ \frac{P[y_t \geq 0 \mid y_{t-1} \geq 0, X]}{P[y_t < 0 \mid y_{t-1} \geq 0, X]} \right\} - \ln \left\{ \frac{P[y_t \geq 0 \mid y_{t-1} < 0, X]}{P[y_t < 0 \mid y_{t-1} < 0, X]} \right\} \right\} \\ &\quad + \ln \left\{ \frac{P[y_t \geq 0 \mid y_{t-1} < 0, X]}{P[y_t < 0 \mid y_{t-1} < 0, X]} \right\} \end{aligned}$$

Hence,

$$\begin{aligned} \tilde{S}_T(\beta_1) &= \sum_{t=1}^T s(y_t) \ln \left\{ \frac{P[y_t \geq 0 \mid \mathbb{S}_{t-1}, X]}{P[y_t < 0 \mid \mathbb{S}_{t-1}, X]} \right\} \\ &= \sum_{t=1}^T s(y_t) \left\{ \begin{array}{l} s(y_{t-1}) \left\{ \ln \left\{ \frac{P[y_t \geq 0 \mid y_{t-1} \geq 0, X]}{P[y_t < 0 \mid y_{t-1} \geq 0, X]} \right\} - \ln \left\{ \frac{P[y_t \geq 0 \mid y_{t-1} < 0, X]}{P[y_t < 0 \mid y_{t-1} < 0, X]} \right\} \right\} \\ + \ln \left\{ \frac{P[y_t \geq 0 \mid y_{t-1} < 0, X]}{P[y_t < 0 \mid y_{t-1} < 0, X]} \right\} \end{array} \right\} \\ &= \sum_{t=1}^T s(y_t) \ln \left\{ \frac{P[y_t \geq 0 \mid y_t < 0, X]}{P[y_t < 0 \mid y_t < 0, X]} \right\} + \sum_{t=1}^T s(y_t) s(y_{t-1}) \left\{ \begin{array}{l} \ln \left\{ \frac{P[y_t \geq 0 \mid y_{t-1} \geq 0, X]}{P[y_t < 0 \mid y_{t-1} \geq 0, X]} \right\} \\ - \ln \left\{ \frac{P[y_t \geq 0 \mid y_{t-1} < 0, X]}{P[y_t < 0 \mid y_{t-1} < 0, X]} \right\} \end{array} \right\} \\ &= \sum_{t=1}^T a_t s(y_t) + \sum_{t=1}^T b_t s(y_t) s(y_{t-1}) \end{aligned}$$

where

$$\tilde{a}_1 = \ln \left\{ \frac{P[y_1 \geq 0 \mid X]}{P[y_1 < 0 \mid X]} \right\} = \ln \left\{ \frac{1 - P[\varepsilon_1 < -\beta'_1 \mathbf{x}_0 \mid X]}{P[\varepsilon_1 < -\beta'_1 \mathbf{x}_0 \mid X]} \right\}$$

$$\tilde{b}_1 = \ln \left\{ \frac{P[y_1 \geq 0 \mid X]}{P[y_1 < 0 \mid X]} \right\} - \ln \left\{ \frac{P[y_1 \geq 0 \mid X]}{P[y_1 < 0 \mid X]} \right\} = 0$$

and for $t = 2, \dots, T$

$$a_t = \ln \left\{ \frac{P[y_t \geq 0 \mid y_t < 0, X]}{P[y_t < 0 \mid y_t < 0, X]} \right\},$$

$$b_t = \ln \left\{ \frac{P[y_t \geq 0 \mid y_{t-1} \geq 0, X]}{P[y_t < 0 \mid y_{t-1} \geq 0, X]} \right\} - \ln \left\{ \frac{P[y_t \geq 0 \mid y_{t-1} < 0, X]}{P[y_t < 0 \mid y_{t-1} < 0, X]} \right\}.$$

Observe that:

$$\begin{aligned} P[y_t \geq 0 \mid y_{t-1} < 0, X] &= 1 - P[y_t < 0 \mid y_{t-1} < 0, X] \\ &= 1 - \frac{P[y_t < 0, y_{t-1} < 0 \mid X]}{P[y_{t-1} < 0 \mid X]} \\ &= 1 - \frac{P[\varepsilon_t < -\beta'_1 \mathbf{x}_{t-1}, \varepsilon_{t-1} < -\beta'_1 \mathbf{x}_{t-2} \mid X]}{P[\varepsilon_{t-1} < -\beta'_1 \mathbf{x}_{t-2} \mid X]}, \end{aligned}$$

$$\begin{aligned} P[y_t < 0 \mid y_{t-1} < 0, X] &= \frac{P[y_t < 0, y_{t-1} < 0 \mid X]}{P[y_{t-1} < 0 \mid X]} \\ &= \frac{P[\varepsilon_t < -\beta'_1 \mathbf{x}_{t-1}, \varepsilon_{t-1} < -\beta'_1 \mathbf{x}_{t-2} \mid X]}{P[\varepsilon_{t-1} < -\beta'_1 \mathbf{x}_{t-2} \mid X]} \end{aligned}$$

$$\begin{aligned} P[y_t \geq 0 \mid y_{t-1} \geq 0, X] &= 1 - P[y_t < 0 \mid y_{t-1} \geq 0, X] \\ &= 1 - \frac{P[y_t < 0, y_{t-1} \geq 0 \mid X]}{P[y_{t-1} \geq 0 \mid X]} \\ &= 1 - \frac{P[y_t < 0 \mid X]}{P[y_{t-1} \geq 0 \mid X]} (P[y_{t-1} \geq 0 \mid y_t < 0, X]) \\ &= 1 - \frac{P[y_t < 0 \mid X]}{P[y_{t-1} \geq 0 \mid X]} (1 - P[y_{t-1} < 0 \mid y_t < 0, X]) \\ &= 1 - \left(\frac{P[y_t < 0 \mid X]}{P[y_{t-1} \geq 0 \mid X]} - \frac{P[y_{t-1} < 0, y_t < 0 \mid X]}{P[y_{t-1} \geq 0 \mid X]} \right) \\ &= 1 - \left(\frac{P[y_t < 0 \mid X]}{1 - P[y_{t-1} < 0 \mid X]} - \frac{P[y_{t-1} < 0, y_t < 0 \mid X]}{1 - P[y_{t-1} < 0 \mid X]} \right) \\ &= 1 - \left[\frac{P[\varepsilon_t < -\beta'_1 \mathbf{x}_{t-1} \mid X]}{1 - P[\varepsilon_{t-1} < -\beta'_1 \mathbf{x}_{t-2} \mid X]} - \frac{P[\varepsilon_{t-1} < -\beta'_1 \mathbf{x}_{t-2}, \varepsilon_t < -\beta'_1 \mathbf{x}_{t-1} \mid X]}{1 - P[\varepsilon_{t-1} < -\beta'_1 \mathbf{x}_{t-2} \mid X]} \right] \end{aligned}$$

$$\begin{aligned} P[y_t < 0 \mid y_{t-1} \geq 0, X] &= \frac{P[y_t < 0, y_{t-1} \geq 0 \mid X]}{P[y_{t-1} \geq 0 \mid X]} \\ &= \frac{P[y_{t-1} \geq 0 \mid y_t < 0, X] P[y_t < 0 \mid X]}{P[y_{t-1} \geq 0 \mid X]} \\ &= \frac{P[y_t < 0 \mid X]}{P[y_{t-1} \geq 0 \mid X]} (1 - P[y_{t-1} < 0 \mid y_t < 0, X]) \\ &= \frac{P[y_t < 0 \mid X]}{1 - P[y_t < 0 \mid X]} - \frac{P[y_{t-1} < 0, y_t < 0 \mid X]}{1 - P[y_t < 0 \mid X]} \end{aligned}$$

$$= 1 - P[y_t \geq 0 \mid y_{t-1} \geq 0, X]$$

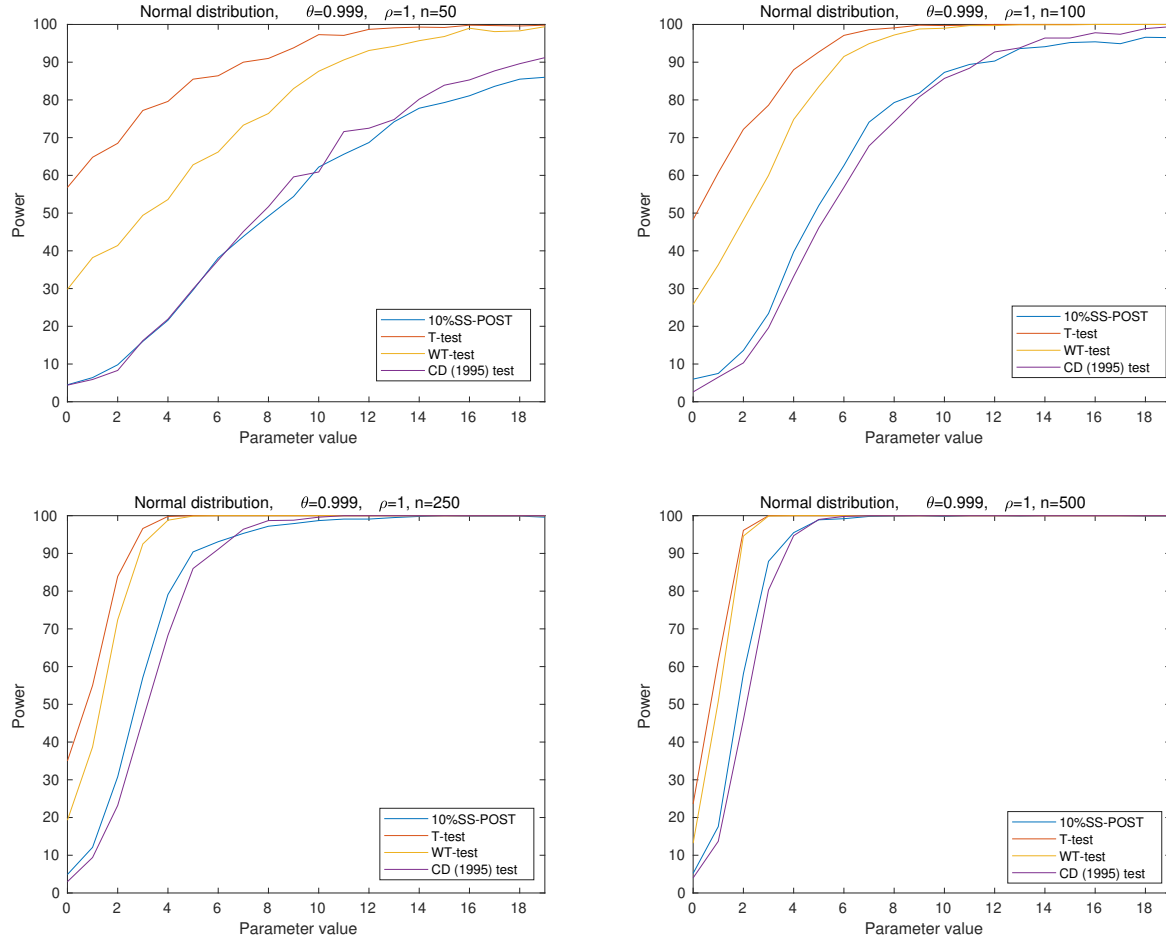
We also have:

$$\begin{aligned}\tilde{a}_1 &= \ln \left\{ \frac{P[y_1 \geq 0 \mid X]}{P[y_1 < 0 \mid X]} \right\} \\ &= \ln \left\{ \frac{1 - P[y_1 < 0 \mid X]}{P[y_1 < 0 \mid X]} \right\} \\ &= \ln \left\{ \frac{1 - P[\varepsilon_1 < -\beta'_1 \mathbf{x}_0 \mid X]}{P[\varepsilon_1 < -\beta'_1 \mathbf{x}_0 \mid X]} \right\} \\ \tilde{b}_1 &= \ln \left\{ \frac{P[y_1 \geq 0 \mid X]}{P[y_1 < 0 \mid X]} \right\} - \ln \left\{ \frac{P[y_1 \geq 0 \mid X]}{P[y_1 < 0 \mid X]} \right\} = 0\end{aligned}$$

■

Additional simulations.

Figure 8: Power comparisons: different tests. Normal distributions with contemporaneous correlation of $\rho = 1$, in (6.3) and local-to-unity autoregression parameter $\theta = 0.999$, in (6.2) for different sample sizes.



Note: These figures compare the power function of the 10% SS-POS test with: (1) the t -test; (2) the sign-based test proposed by Campbell and Dufour (1995) [CD (1995) test]; and (3) the t -test based on White's (1980) variance correction [WT-test].

■